Subset Selection Procedures for $\label{eq:Restricted} \textbf{Restricted Families of Probability Distributions}^{\dagger}$

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ABSTRACT

In this paper we are interested in studying multiple decision procedures for $k(k \ge 2)$ populations which are themselves unknown but which one assumed to belong to a restricted family. We propose to study a selection procedure for distributions associated with these populations which are convex-ordered with respect to a specified distribution G assuming that there exists a best one. The procedure described here is based on a statistic which is a linear function of the first r order statistics and which reduces to the total life statistics when G is exponential. The infimum of the probability of a correct selection and an asymptotic expression for this probability are obtained using the subset selection approach. Some other properties of this procedure are discussed. Asymptotic relative efficiencies of this rule with respect to some selection procedures proposed by Barlow and Gupta (1969) for the star-ordered distributions and by Gupta (1969) for the gamma populations with unknown shape parameters are obtained. A selection procedure for selecting the best population using the indifference zone approach is also studied.

SELECTION PROCEDURES FOR RESTRICTED FAMILIES

OF PROBABILITY DISTRIBUTIONS*

1. Introduction

In many problems, especially those in reliability theory, one is interested in using a model for life length distribution which is not completely specified but belongs, for example, to a family of distributions having increased failure rate (IFR), or increasing failure rate on the average (IFRA). Such distributions form special cases of what are now commonly known as restricted families of probability distributions. The idea of using such families stems from the fact that in many cases the experimenter cannot specify the model (distribution) exactly but is able to say whether it comes from a family of distributions such as IFR, IFRA. Families of probability distributions of these types have been studied by several authors, see, for example, Barlow, Marshall and Proschan [4], Barlow and Proschan [5,6] and Barlow and Doksum [1].

In this paper we are interested in studying multiple decision procedures for $k(k \ge 2)$ populations which are themselves unknown but which are assumed to belong to a restricted family. We now give some definitions of interest to us (see Barlow and Gupta [3]).

- (i) F is said to be convex with respect to G (written F ${<\atop c}$ G) if and only if ${\hbox{\rm G}}^{-1}F(x)$ is convex on the support of F .
- (ii) F is said to be star-shaped with respect to G (written F \leqslant G) if and only if F(0) = G(0) = 0 and $\frac{G^{-1}F(x)}{x}$ is increasing in $x\geq 0$ on the support of F .

If $G(x)=1-e^{-x}$, $x\geq 0$, then $F\leqslant G$ is equivalent to saying that F has increasing failure rate (IFR). Again if $G(x)=1-e^{-x}$, $x\geq 0$, $F \nleq G$ is

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equivalent to saying that F has increasing failure rate on average (IFRA).

In the statistical literature, selection problems for restricted families were first investigated by Barlow and Gupta [3]. Some further results in this direction and a review of some important results concerning inequalities for restricted families and problems of inference for such families have been given by Gupta and Panchapakesan [10,11] and Patel [16].

In Section 2, we propose and study a subset selection rule for distributions which are < ordered with respect to a specified distribution G assuming there exists a best one. Some properties of this rule are discussed. The infimum of the probability of a correct selection is obtained and an asymptotic expression is also given. We also study the asymptotic relative efficiencies of this rule with respect to some selection procedures. Section 3 deals with selecting the best population using the indifference zone approach.

2. Selection rules for distributions $\stackrel{<}{\mbox{c}}$ ordered with respect to a specified distribution G .

Before discussing the selection problem, we give some preliminary known results for sake of completeness. Let F be the class of absolutely continuous distribution functions F on R such that F(0)=0 with positive and right-(or left-) continuous density f on the interval where 0 < F < 1. For $F \in F$, we take $F^{-1}(1)$ to be equal to the right hand endpoint of the support of F and we define $F^{-1}(0)=0$. For F, $G \in F$, consider the following transformation (see Barlow and Doksum [1])

(2.1)
$$H_{F}^{-1}(t) = \int_{0}^{F^{-1}(t)} g[G^{-1}F(u)]du , \quad 0 \le t \le 1 ,$$

where g denotes the density of G .

We assume that G is always fixed. Since $\mathrm{H_F}^{-1}$ (the inverse of $\mathrm{H_F}$) is strictly increasing on [0,1], $\mathrm{H_F}$ is a distribution. Barlow and Doksum [1] have shown that $\mathrm{F_C}$ G if and only if $\mathrm{H_F}$ is convex on the interval where $0 < \mathrm{H_F} < 1$. Since G is assumed known we can estimate $\mathrm{H_F}^{-1}$ by substituting the empirical distribution $\mathrm{F_n}$ of F; that is

(2.2)
$$H_n^{-1}(t) = H_{F_n}^{-1}(t) = \int_0^{F_n^{-1}(t)} g[G^{-1}F_n(u)]du$$

(2.3)
$$H_n^{-1}(\frac{\mathbf{r}}{n}) = \int_0^{X_{\mathbf{r}}} g[G^{-1}F_n(u)] du = \sum_{i=1}^{r} g[G^{-1}(\frac{i-1}{n})](X_{i,n} - X_{i-1,n})$$

where $X_{i,n}$ is the i^{th} order statistic in a sample of size n from F and $X_{0,n} \equiv 0$.

If $G(x) = 1 - e^{-x}$ for $x \ge 0$, then (2.3) can be written as

(2.4)
$$H_{n}^{-1}(\frac{r}{n}) = \frac{1}{n} \left[X_{1,n} + \dots + X_{r-1,n} + (n-r+1)X_{r,n} \right] .$$

We say that $X_{1,n} + \cdots + X_{r-1,n} + (n-r+1)X_{r,n}$ is the total life statistic until r^{th} failure from F .

(A) Selection procedure and its properties

Let π_1,\dots,π_k be k populations. The random variable X_i associated with π_i has distribution function F_i , $i=1,2,\dots,k$, where $F_i \in \mathcal{F}$. Let $F_{[k]}$ denote the cumulative distribution function (c.d.f) of the "best" population. We assume that (a) $F_i(x) \geq F_{[k]}(x)$ for all x, $i=1,\dots,k$ and (b) there exists a distribution G such that $F_i \leq G$, $i=1,\dots,k$, where \leq denotes a partial ordering relation on the space of probability distributions. We are given a sample of size n from each $\pi_i(i=1,\dots,k)$. Our goal is to select a subset from the k populations so as to include

the population with $F_{[k]}$. Let $\Omega = \{\underline{F} = (F_1, \cdots, F_k) : \exists \text{ a j} \text{ such that } F_i(x) \geq F_j(x) \text{ for all } x \text{ and } i = 1, 2, \dots, k\}$. Let

(2.5)
$$T_{i} = \sum_{j=1}^{r} a_{j}X_{i;j,n} \quad \text{for } i=1,\dots,k \text{ and}$$

(2.6)
$$T = \sum_{j=1}^{r} a_{j}Y_{j,n}$$

where $X_{i;j,n}$ is the jth order statistic from $F_i,Y_{j,n}$ is the jth order statistic from G,r is a fixed positive integer $(1 \le r \le n)$, $a_j = gG^{-1}(\frac{j-1}{n}) - gG^{-1}(\frac{j}{n})$ for $j=1,\ldots,r-1$ and $a_r = gG^{-1}(\frac{r-1}{n})$.

For selecting a subset containing $\ F_{[k]}$, we propose the selection rule R_1 as follows:

 R_1 : Select population π_i if and only if

where $c_1 = c_1(k, P^*, n, r)$ is the largest number between 0 and 1 which is determined as to satisfy the probability requirement

(2.8)
$$\inf_{\Omega} P [CS | R_1] \ge P^*$$

where CS stands for a correct selection, i.e., the selection of any subset which contains the population with distribution $F_{[k]}$. For a given $\alpha(0 < \alpha < 1)$, we assume each F_{i} has a unique α -quantile. Let $F_{[i]}(x) = F_{[i]}$ denote the cumulative distribution function of the population with i^{th} smallest α -quantile. Let $T_{(i)}$ be associated with $F_{[i]}$ and let $W_{i}(x)$ be the c.d.f. of $T_{(i)}$.

Lemma 2.1. Let F_1 , F_2 be two distribution functions such that $F_1(x) \ge F_2(x) \forall x$ and $T_i = \sum_{j \in \Delta} b_j X_{i;j,n}$ i = 1,2, where $b_j > 0$ for $j \in \Delta$, $\Delta \subset \{1,2,\ldots,n\}$ and $X_{i;j,n}$ is the jth order statistic from F_i , i = 1,2, then $P[T_1 \le x] \ge P[T_2 \le x]$.

Proof. Let
$$\Psi(X_{i1},...,X_{in}) = \begin{cases} 1 & \text{if } T_{i} \ge x \\ 0 & \text{otherwise} \end{cases}$$

where X_{i1},\dots,X_{in} are n observations from F_i (i = 1,2). Since $\psi(X_{i1},\dots,X_{in})$ is nondecreasing in each of its arguments, it follows by induction (Lehmann [15] p. 112) that $E\psi(X_{i1},\dots,X_{in}) \leq E\psi(X_{21},\dots,X_{2n})$. That is $P[T_1 \geq x] \leq P[T_2 \geq x]$. This proves the lemma.

We now state and prove the following theorem which is more general than that of Patel [16].

Theorem 2.1. If F_i , $G \in F$, $F_i(x) \ge F_{[k]}(x) \ \forall x$ and $i=1,2,\ldots,k$, $F_{[k]} \le G$, $a_j \ge 0$ for $j=1,2,\ldots,r$, $g(0) \le 1$ and $a_r \ge c_1$, then

(2.9)
$$\inf_{\Omega} P[CS|R_1] = \int_{0}^{\infty} G_T^{k-1}(\frac{x}{c_1}) dG_T(x)$$

where $G_T(x)$ is the c.d.f. of T.

Proof.

$$P[CS | R_{1}] = P[T_{(k)} \ge c_{1}T_{(i)}, i = 1,...,k-1]$$

$$= \int_{0}^{\infty} \frac{k_{\overline{1}}1}{1!} W_{i} \left(\frac{x}{c_{1}}\right) dW_{k}(x)$$

$$\ge \int_{0}^{\infty} W_{k}^{k-1} \left(\frac{x}{c_{1}}\right) dW_{k}(x) \quad (By Lemma 2.1)$$

$$= P[Z_{k} \ge c_{1}Z_{j}, j = 1,...,k-1]$$

where Z_1 , ..., Z_k are i.i.d. with c.d.f. $W_k(x)$. Let $\phi(x) = G^{-1}F_{\lceil k \rceil}(x)$. Note that $\phi(x)$ is nondecreasing in x . Also we can write

(2.10)
$$Z = \sum_{\substack{i \text{ st } j=1}}^{r} a_{i} X_{i,n}^{*} \qquad i = 1, \dots, k ,$$

where $X_{i;j,n}^*$ is the jth order statistic in a sample of size n from $F_{[k]}$, $i=1,\ldots,k$.

(2.11)
$$P[Z_{k} \ge c_{1} \max_{1 \le j \le k} Z_{j}] = P[\phi(\frac{1}{c_{1}} Z_{k}) \ge \phi(Z_{j}), \quad i = 1, \dots, k-1].$$

Since $\sum_{j=1}^{r} a_j = g(0) \le 1$, $a_j \ge 0 \ \forall j=1,\ldots,r$, and $\phi(0)=0$, by Lemma 4.1 of Barlow and Proschan [5] and (2.10), then

(2.12)
$$\phi(Z_i) \leq \sum_{j=1}^{r} a_j \phi(X_{i;j,n}^*) .$$

Since $\frac{1}{c_1}$ $a_r \ge 1$, $\frac{1}{c_1}$ $\sum_{j=1}^r$ $a_j \ge 1$ for $i=1,\ldots,r$, and $\phi(0)=0$, by Lemma 4.3 of Barlow and Proschan [5] and (2.10), we have

$$(2.13) \qquad \qquad \phi(\frac{1}{c_1} Z_k) \underset{\text{st}}{\geq} \frac{1}{c_1} \sum_{j=1}^{r} a_j \phi(X_k^*; j, n) .$$

$$\phi(X_{i;j,n}^*) = Y_{i;j,n}$$

where $Y_{i;j,n}$ is the jth order statistic from G , $i=1,2,\ldots,k$. Thus from (2.11), (2.12), (2.13), and (2.14),

$$P[Z_{k} \geq c_{1} \max_{1 \leq i \leq k} Z_{i}] \geq P[\sum_{j=1}^{r} a_{j}Y_{k;j,n} \geq c_{1} \sum_{j=1}^{r} a_{j}Y_{i;j,n}, i=1,...,k-1]$$

$$= \int_{0}^{\infty} G^{k-1}(\frac{x}{c_{1}}) dG_{T}(x)$$

This completes the proof.

The constant $c_1 = c_1(k, P^*, n, r)$ satisfying (2.8) is the largest number between 0 and 1 determined by

$$\int_{0}^{\infty} G_{T}^{k-1} \left(\frac{x}{c_{1}}\right) dG_{T}(x) \ge P^{*} \quad \text{and} \quad gG^{-1}\left(\frac{r-1}{n}\right) \ge c_{1} \quad .$$

We now consider two specific distributions G(x). If $G(x) = 1 - e^{-x}$, $x \ge 0$, then we have following result which slightly generalizes the result of Patel [16].

Corollary 2.1. If $F_i(x) \ge F_{[k]}(x) \forall x$ and i=1,...,k, $F_{[k]} \le G$, $G(x)=1-e^{-x}$ x>0 and $n \ge \max\{r, \frac{r-1}{1-c_1}\}$, then

(2.15)
$$\inf_{\Omega} P[CS | R_1] = \int_{0}^{\infty} H^{k-1}(\frac{x}{c_1}) dH(x)$$

where H(x) is the c.d.f. of a χ^2 random variable with 2r d.f.

Proof. If $G(x) = 1 - e^{-x}$ then $a_j = \frac{1}{n}$ for $j = 1, 2, \ldots, r-1$ and $a_r = \frac{1}{n}(n-r+1)$. Also $\frac{1}{c_1} a_r \ge 1$ iff $n \ge \frac{r-1}{1-c_1}$. By Theorem 2.1 and the fact that 2nT is distributed as χ^2 with 2r d.f., the result follows.

If G(x) = x for 0 < x < 1, then we have the following result which is a special case of Theorem 2.1 of Barlow and Gupta [3].

Corollary 2.2. If $F_i(x) \ge F_{[k]}(x) \ \forall x$ and $i=1,\dots,k$, $F_{[k]} \ \stackrel{<}{<} \ G$ and G(x)=x for $0 \le x \le 1$, then

$$(2.16) \quad \inf_{\Omega} P[CS|R_1] = n \binom{n-1}{r-1} \int_{0}^{\infty} \left[\sum_{i=r}^{n} \binom{n}{i} \left(\frac{x}{c_1} \right)^i \left(1 - \frac{x}{c_1} \right)^{n-i} \right]^{k-1} x^{r-1} (1-x)^{n-r} dx .$$

Actually, the condition $F_{[k]} \leq G$ in Corollary 2.2 can be relaxed to

 $F_{[k]} \stackrel{\leq}{\star} G$.

We state and prove the following theorem about the asymptotic evaluations of the probability of a correct selection associated with the rule R_1 in the case where r is so chosen that $r \leq (n+1)\alpha < r+1$, $0 < \alpha < 1$. This amounts to selecting populations with large values of the α -quantile for α (and r) as defined above. In this case, $\frac{r}{n} \rightarrow \alpha$ as $n \rightarrow \infty$. Note that the result holds for all α .

Theorem 2.2. If F_i , $G \in F$ for all i = 1,...,k and

(i)
$$F_{i}(x) \ge F_{[k]}(x) \forall x, i = 1,...,k, F_{[k]} \le G$$

- (ii) G(x) has a differentiable density g in a neighborhood of its $\alpha-quantile\ \eta_{\alpha}\ ,\ g(\eta_{\alpha})\neq 0\ ,\ and$
- (iii) gG^{-1} is uniformly continuous on [0,1], $G^{-1}(x)$ is convex and there exists an ξ , $0<\xi<1$, such that for $\xi\leq y<1$, $\frac{gG^{-1}(y)}{1-y}$ is nondecreasing in y, then as $n\to\infty$

(2.17)
$$P[CS|R_1] \ge \int_{-\infty}^{\infty} \Phi^{k-1} \left[\frac{x}{c_1} + \frac{1-c_1}{c_1} \eta_{\alpha} g(\eta_{\alpha}) \left(\frac{n}{\alpha \overline{\alpha}} \right)^{1/2} \right] d\Phi(x)$$

where $\bar{\alpha} = 1 - \alpha$ and $\Phi(x)$ is the standard normal c.d.f.

Proof. We note that

(2.18)
$$P[CS|R_1] \ge P[Z_k \ge c_1 \max_{1 \le j \le k} Z_j]$$

where Z_1, \dots, Z_k are i.i.d. with c.d.f $W_k(x)$ and $W_k(x)$ is the c.d.f. of $T_{(k)}$.

By Theorem (2.2) of Barlow and Van Zwet [7] and condition (iii), then we have (see Barlow and Doksum [1]), for n large,

$$(2.20) Z_{i \text{ st } i;r,n}$$

where $Y_{i;r,n}$ is the r^{th} order statistic from H_F and H_F^{-1} (the inverse of H_F) is defined in (2.1). Now $F_{[k]} \subset G$ if and only if H_F is convex. Since $G^{-1}(x)$ is increasing and convex, it follows that $G^{-1}H_F^{-1}(x)$ is convex. Since $H_F \subset G$ and $G^{-1}(0) = 0$, then $H_F \subset G$. In a manner similar to the theorem (2.1) of Barlow and Gupta [3], we have

(2.21)
$$P[Y_{k;r,n} \ge c_1 \max_{1 \le i \le k} Y_{i;r,n}] \ge P[Y_{k;r,n}^* \ge c_1 Y_{i;r,n}^*, i \ne k]$$

where $Y_{i;r,n}^*$ is the r^{th} order statistic from G, $i=1,\ldots,k$. From (2.18), (2.20), (2.21) and using the fact that

(2.22)
$$Y_{i;r,n}^* \sim N(\eta_{\alpha}, \frac{\alpha \overline{\alpha}}{ng^2(\eta_{\alpha})}),$$

the theorem follows.

Before we discuss some properties of the selection rule \mbox{R}_1 , we introduce some definitions (see Santner [17]).

Define $P_{\underline{F}}(i) = P_{\underline{F}}[\pi_{(i)}]$ is selected R] where $\pi_{(i)}$ is associated with F[i].

Definition 2.1.

(i) A rule R is strongly monotone in $\pi_{(i)}$ if

$$P_{\underline{F}}(i) \quad \text{is} \quad \begin{cases} \uparrow \text{in} \quad F_{\texttt{[i]}} \quad \text{when all other components of } \underline{F} \quad \text{are fixed} \\ \\ \psi \text{in} \quad F_{\texttt{[j]}}(j \neq i) \quad \text{when all other components of } \underline{F} \quad \text{are fixed.} \end{cases}$$

That means, $P_{\underline{F_1}}(i) \ge P_{\underline{F_2^*}}(i)$ when $F_{[i]} \ge F_{[i]}^*$ and $P_{\underline{F_2}}(j) \le P_{\underline{F_2^*}}(j)$ when $F_{[j]} \ge F_{[j]}^*$ for $j \ne i$, where $\underline{F_1} = (F_{[1]}, \dots, F_{[i]}, \dots, F_{[k]})$, $\underline{F_2^*} = (F_{[1]}, \dots, F_{[i]}, \dots, F_{[k]})$ and $\underline{F_2^*} = (F_{[1]}, \dots, F_{[i]}, \dots, F_{[k]})$.

- (ii) A rule R is monotone means $P_{\underline{F}}(i) \leq P_{\underline{F}}(j)$ for all $\underline{F} \in \Omega$ with $F_{[i]}(x) \geq F_{[i]}(x)$.
- (iii) A rule R is unbiased if $P_{\underline{F}}(i) \leq P_{\underline{F}}(k)$ for all $\underline{F} \in \Omega$ with $F_{[i]}(x) \geq F_{[k]}(x)$.
- (iv) A rule R is consistent with respect to Ω' means $\inf_{\Omega'} \ P[\,CS\big|\,R\,] \to 1 \quad \text{as} \quad n \to \infty \quad .$

It is similar to the proof in Lemma 2.1, we can show the following theorem.

Theorem 2.3. If $a_{\underline{i}} \ge 0$ for i = 1, ..., r, then $R_{\underline{i}}$ is strongly monotone in $\pi_{(\underline{i})}$.

Remark 2.1.

(1) If a rule R is strongly monotone in $\pi_{(i)}$ for all $i=1,\dots,k$, then R is monotone and inf $P[CS|R]=\inf P[CS|R]$ where Ω

$$\Omega_0 = \{\underline{F} = (F_1, \dots, F_k) \in \Omega : F_1 = \dots = F_k\}$$

- (2) If R is monotone. then it is unbiased.
- (3) If $F_i(x) = F(x, \theta_i)$, $i = 1, \dots, k$ and T_i is a consistent estimator of θ_i , then R_1 is consistent with respect to $\Omega = \{\underline{F} = (F_1, \dots, F_k) : \exists \ a \ j \ such that <math>F_i(x) \geq F_j(x)$ for all x and $i = 1, \dots, k\}$.
- (4) If F , G ϵ F , F $_i$ C , i = 1,...,k and the condition (iii) of Theorem 2.2 is satisfied, we can show that R is consistent with respect to Ω .

The selection of the population with largest F_i (i = 1,...,k) can be handled analogously. We assume $F_{[i]}(x) \leq F_{[1]}(x)$, i = 1,...,k, and $F_{[1]}(x) \leq G$. The rule for selecting the population with $F_{[1]}(x) \leq G$ is $G_{[1]}(x) \leq G$. Select population $G_{[1]}(x) \leq G$.

$$\begin{array}{cccc} c_2^T_i & \leq \min & T_j \\ 1 \leq j \leq k \end{array}$$

where $c_2(0 < c_2 < 1)$ is determined so as to satisfy the basic requirement. In a manner similar to the proof of Theorem 2.1, we have

Theorem 2.4. If F_i , $G \in F$, $F_{[i]}(x) \leq F_{[1]}(x) \forall x$ and $i=1,\ldots,k$, $F_{[1]} \subset G$, $a_j \geq 0$ for $j=1,\ldots,r$, $g(0) \leq 1$ and $a_r \geq c_2$, then

(2.24)
$$\inf_{\Omega'} P[CS|R_2] = \int_0^\infty \overline{G}_T^{k-1} (c_2x) dG_T(x)$$

where $\overline{G}_T(x) = 1 - G_T(x)$ and $\Omega' = \{\underline{F} = (F_1, \dots, F_k) : \exists \ a \ j \ \text{such that} \ F_i(x) \leq F_j(x) \}$ for all x and $i = 1, \dots, k\}$.

(B) Efficiency of procedure R₁ under slippage configuration.

Under the same notations and conditions of Theorem 2.2 and the comments above the Theorem 2.2, we consider slippage configuration $F_{[i]}(x) = F\left(\frac{x}{\delta}\right)$, $i=1,2,\ldots,k-1$, and $F_{[k]}(x) = F(x)$, $0 < \delta < 1$. Let E(S|R) denote the expected subset size using the rule R. Then E(S|R) - P[CS|R] is the expected number of non-best populations included in the selected subset. For a given $\varepsilon > 0$, let $n_R(\varepsilon)$ be the asymptotic sample size for which $E(S|R) - P[CS|R] = \varepsilon$. We define the asymptotic relative efficiency $ARE(R,R^*,\delta)$ of R relative to R^* to be the limit as $\varepsilon \to 0$ of the ratio $\frac{n_R(\varepsilon)}{n_{R^*}(\varepsilon)}$ i.e. $ARE(R,R^*;\delta) = \lim_{\varepsilon \to 0} \frac{n_R(\varepsilon)}{n_{R^*}(\varepsilon)}$. Under the slippage configuration we have,

(2.25)
$$E(S|R_1) = P[CS|R_1] + (k-1)P[T_{(1)} \ge c_1 \max_{i \ne 1} T_{(i)}]$$

If n is large, then from an argument similar to the one in the proof of Theorem 2.2, we have

(2.26)
$$P[T_{(1)} \ge c_1 \max_{i \neq 1} T_{(i)}] \approx P[Y_1 \ge c_1 \max_{i \neq 1} Y_i]$$

where Y_1, \dots, Y_k are independent and Y_i is the r^{th} order statistic from H_F for $i=1,\dots,k$. The right hand side of (2.26) is asymptotically equal to $\int_{-\infty}^{\infty} \Phi\left(\frac{\delta x}{c_1} - a_{\alpha}h(a_{\alpha})(1-\frac{\delta}{c_1})(\frac{n}{\alpha\overline{\alpha}})^{1/2}\right).$

$$\Phi^{k-2}(\frac{x}{c_1}-a_\alpha h(a_\alpha)(1-\frac{1}{c_1})(\frac{n}{\alpha\overline{\alpha}})^{1/2})d\Phi(x)$$

where c_1 is the constant used in defining R_1 , a_{α} is the (unique)

 α - quantile of H $_F$ (x) and h(x) is the density function of H $_F$ (x) . For k = 2 and n large,

$$(2.28) \quad \mathbb{E}(\mathbf{S} | \mathbf{R}_1) - \mathbb{P}[\mathbf{C} \mathbf{S} | \mathbf{R}_1] \approx \Phi(-\mathbf{h}(\mathbf{a}_{\alpha}) \mathbf{a}_{\alpha} (1 - \frac{\delta}{c_1}) (\frac{\mathbf{n}}{\alpha \overline{\alpha}})^{1/2} (1 + \frac{\delta^2}{c_1^2})^{-1/2}) \quad .$$
 Let
$$\int_{-\infty}^{\infty} \Phi^{\mathbf{k}-1} (\frac{\mathbf{x}}{c_1} + (1-c_1) \eta_{\alpha} \mathbf{g}(\eta_{\alpha}) \frac{1}{c_1} (\frac{\mathbf{n}}{\alpha \overline{\alpha}})^{1/2}) d\Phi(\mathbf{x}) = \mathbf{P}^* \quad .$$

Now setting the right side of (2.28) equal to ϵ and using $c_1 \approx 1 - \frac{2^{1/2}D}{n^{1/2}}$, where $D = \Phi^{-1}(p^*)(\alpha \overline{\alpha})^{1/2}/\eta_{\alpha}$ g(η_{α}), we obtain

(2.29)
$$n_{R_1}(\varepsilon) \approx [-(\alpha \bar{\alpha})^{1/2} \Phi^{-1}(\varepsilon) (1+\delta^2)^{1/2} + \sqrt{2} D \delta a_{\alpha} h(a_{\alpha})]^2.$$

$$[a_{\alpha}^2 h^2(a_{\alpha}) (1-\delta)^2]^{-1}.$$

Comparison with Barlow-Gupta Procedure

Barlow and Gupta [3] propose a procedure R_3 , for the quantile selection problem of star-ordered distributions which is,

 R_3 : Select population π_i if and only if

$$T_{r,i} \ge c_3 \max_{1 \le i \le k} T_{r,j}$$

where $c_3(0 < c_3 < 1)$ is chosen to satisfy $P[CS \mid R_3] \ge P^*$ and $T_{r,i}$ is the r^{th} order statistic from F_i where $r \le (n+1)\alpha < r+1$. They derive an expression for $n_{R_3}(\epsilon)$ as follows:

$$n_{R_{3}}(\varepsilon) \approx [-(\alpha \bar{\alpha})^{1/2} \Phi^{-1}(\varepsilon) (1 + \delta^{2})^{1/2} + \sqrt{2} D\delta \xi_{\alpha} f(\xi_{\alpha})]^{2} [\xi_{\alpha}^{2} f^{2}(\xi_{\alpha}) (1 - \delta)^{2}]^{-1}$$

where f is the density of F with unique $\alpha\text{--quantile, }\xi_{\alpha}$.

(2.31)
$$\operatorname{ARE}(R_1, R_3; \delta) = \lim_{\varepsilon \to 0} \frac{\operatorname{n}_{R_1}(\varepsilon)}{\operatorname{n}_{R_3}(\varepsilon)} = \frac{\xi_{\alpha}^2 f^2(\xi_{\alpha})}{a_{\alpha}^2 h^2(a_{\alpha})}.$$

If $G(x) = 1 - e^{-x}$, x > 0 and $F_{[1]}(x) = 1 - e^{-x/\delta}$ and $F_{[2]}(x) = 1 - e^{-x}$, $x \ge 0$, $0 < \delta < 1$, we have,

(2.32)
$$ARE(R_1, R_3; \delta) = \frac{(1-\alpha)^2 \log^2(1-\alpha)}{\alpha^2} \le 1$$

$$= 0.4803, \alpha = 1/2.$$

Comparison with Gupta Procedure

Gupta [8] gave a selection procedure for gamma populations $\pi_{\bf i}$'s with densities $\frac{1}{\Gamma(a)\theta_{\bf i}^a}$ $x^{a-1}e^{-x/\theta_{\bf i}}$ x>0 , $\theta_{\bf i}>0$, i=1,2,...,k . The procedure R_4 is

 R_4 : Select population π_i if and only if

$$(2.33) \bar{X}_{i} \geq c_{4} \max_{1 \leq j \leq k} \bar{X}_{j}$$

where \overline{X}_1 is the sample mean of size n from π_1 and c_4 is the largest constant $(0 < c_4 < 1)$ chosen so that $P[CS | R_4] \ge P^*$.

For k=2, $\theta_{[1]}=\delta$ and $\theta_{[2]}=1$ (see Barlow and Gupta [3]), we have

(2.34)
$$\operatorname{ARE}(R_3, R_4; \delta) = \lim_{\epsilon \to 0} \frac{n_{R_3}(\epsilon)}{n_{R_4}(\epsilon)} = \frac{a(\log \delta)^2 \alpha \overline{\alpha}(1 + \delta^2)}{2(1 - \delta)^2 [\xi_{\alpha} f(\xi_{\alpha})]^2}.$$

Hence

(2.35)
$$ARE(R_1, R_4; \delta) = ARE(R_1, R_3; \delta) ARE(R_3, R_4; \delta)$$

$$= \frac{\sqrt{a} \log \delta \sqrt{\alpha \bar{\alpha}} \sqrt{1 + \delta^2}}{\sqrt{2} (1 - \delta) a_{\alpha} h(a_{\alpha})}^2.$$

If $G(x) = 1 - e^{-x}$ for x > 0 and a = 1,

(2.36)
$$ARE(R_1, R_4; \delta) = \frac{(1-\alpha)(1+\delta^2) \log^2 \delta}{2(1-\delta)^2 \alpha}$$

(2.37)
$$ARE(R_1,R_4;\delta\uparrow 1) = \frac{1-\alpha}{\alpha} .$$

Comparison of R₁ and R₅ from uniform distribution

Suppose π_1 and π_2 are two independent uniform populations with distribution functions F, (i=1,2) .

(2.38)
$$F_{\mathbf{i}}(\mathbf{x}) = \begin{cases} 0 & \mathbf{x} < 0 \\ \frac{\mathbf{x}}{\theta_{\mathbf{i}}} & 0 \le \mathbf{x} \le \theta_{\mathbf{i}} \\ 1 & \mathbf{x} > \theta_{\mathbf{i}} \end{cases}$$

where $\delta = \theta_{[1]} < \theta_{[2]} = 1$.

A sample of n independent observations is drawn from each of the two populations. Let T_i^* be the total life statistic until r^{th} failure from π_i (i=1,2) where $r \le (n+1)\alpha < r+1$. The procedure R_5 is given by

 R_5 : Select population π_i if and only if

$$T_{i}^{*} \geq c_{5} \max_{1 \leq i \leq k} T_{j}^{*}$$

where $c_5^{}$ is chosen so that $\left. \text{P[CS} \right| \text{R}_5^{}] \geq \text{P*}$.

Let $T_{(i)}^*$ be associated with $\theta_{[i]}$.

(2.40)
$$E(S|R_5) - P[CS|R_5] = P[T_{(1)}^* \ge c_5 T_{(2)}^*] = P[T_1^* \ge \frac{c_5}{\delta} T_2^*]$$

where T_1^{\dagger} , T_2^{\dagger} are two independent total life statistic until r^{th} failure from uniform distribution over (0,1). By Gupta and Sobel [12],

(2.41)
$$\frac{T_{i}^{\dagger} - u}{\sigma} \rightarrow N(0,1) \quad \text{as} \quad n \rightarrow \infty \quad ,$$

where
$$u = \frac{n\alpha(2n - \alpha n + 1)}{2n + 1} \approx u^{\dagger} = \frac{n\alpha(2 - \alpha)}{2}$$
, $\sigma^2 = An$ and $A = \frac{\alpha(1 - \alpha)(2 - \alpha)^2}{4} + \frac{\alpha^3}{12}$. Hence $\frac{u}{\sigma} \approx \frac{u^{\dagger}}{\sigma} = B\sqrt{n}$ where $B = \frac{\alpha(2 - \alpha)}{2\sqrt{A}}$. From (2.40), we have
$$E(S|R_5) - P[CS|R_5] \approx P[Z_1 \ge \frac{c_5}{\delta} Z_2 + (\frac{c_5}{\delta} - 1)B\sqrt{n}]$$

where Z_1 , Z_2 are i.i.d. with N(0,1) .

$$E(S|R_{5}) - P[CS|R_{5}] = \int_{-\infty}^{\infty} \Phi[\frac{\delta}{c_{5}} \times -(1 - \frac{\delta}{c_{5}})B\sqrt{n}]d\Phi(x)$$

$$= \Phi[-(1 - \frac{\delta}{c_{5}})B\sqrt{n} / \sqrt{1 + (\frac{\delta}{c_{5}})^{2}}]$$

Let $E(S|R_5) - P[CS|R_5] = \varepsilon > 0$, we obtain

(2.42)
$$\left(\frac{1}{c_5} - \frac{1}{\delta}\right)\sqrt{n} = \sqrt{\frac{1}{\delta^2} + \frac{1}{c_5^2}} \cdot \frac{\Phi^{-1}(\epsilon)}{B}$$

Note that $\inf_{\Omega} P[CS | R_5] = P[T_1^! \ge c_5 T_2^!]$,

$$\approx \phi[-(1-\frac{1}{c_5})B\sqrt{n}/\sqrt{1+1/c_5^2}]$$

where T_1^{\dagger} and T_2^{\dagger} are defined as above.

Setting inf P[CS|R₅] = P* and using
$$c_5 \approx 1 - \frac{\sqrt{2}\Phi^{-1}(P^*)}{\sqrt{n} B}$$
 and $\frac{1}{c_5} \approx 1 + \frac{\sqrt{2}\Phi^{-1}(P^*)}{\sqrt{n} B}$, from (2.42), we obtain

$$(2.43) n_{R_5}(\varepsilon) \approx \left\{ \frac{\Phi^{-1}(\varepsilon)\sqrt{1+\delta^2} - \sqrt{2}\delta\Phi^{-1}(p^*)}{B(1-\delta)} \right\}^2 .$$

From (2.29) and (2.43),

(2.44)
$$\operatorname{ARE}(R_{1}, R_{5}; \delta) = \lim_{\varepsilon \to 0} \frac{n_{R_{1}}(\varepsilon)}{n_{R_{5}}(\varepsilon)} = \frac{\alpha \bar{\alpha} B^{2}}{a_{\alpha}^{2} h^{2}(a_{\alpha})}$$

If we assume that G(x) = x for $0 \le x \le 1$, then

(2.45)
$$ARE(R_{1}, R_{5}; \delta) = \frac{B^{2}(1-\alpha)}{\alpha} = \frac{3(1-\alpha)(2-\alpha)^{2}}{3(1-\alpha)(2-\alpha)^{2}+\alpha^{2}} < 1$$

ARE(R_1, R_5 ; δ) is a decreasing function of α and for $\alpha = 1/2$, it is equal to 0.931. Note that in (2.45), R_1 is based on r^{th} ordered statistic and R_5 is based on the total life statistic until r^{th} failure.

(C) Selection procedure for distribution < ordered with respect to Weibull distribution

Assume that the specified distribution G(x) is given by

$$G(x) = \begin{cases} 1 - e^{-\lambda x^{\alpha}} & \text{for } x \ge 0 \\ 0 & \text{for } x < 0 \end{cases}$$

where $\lambda>0$ and attention is restricted to $\alpha\geq 1$ which is assumed known. In this case, we use T_1^* as our statistic where

$$T_{i}^{*} = \sum_{j=1}^{r-1} X_{i;j,n}^{\alpha} + (n-r)X_{i;r,n}^{\alpha}$$
, $i = 1,...,k$.

As before, $X_{i;j,n}$ denote the j^{th} order statistic from F_i , $i=1,\dots,k$. Since G(x) is convex with respect to the exponential distribution if $\alpha \geq 1$ and since the convex ordering is transitive, the family of distributions which are convex

with respect to Weibull $(\alpha \ge 1)$ will have IFR distribution. Thus our interest here is in a special subclass of IFR distributions. The rule for selecting the population which is assoicated with $F_{\lceil k \rceil}$ is as follows,

 R_6 : Select population π_i if and only if

$$\begin{array}{ccc}
 & \text{T*} \geq c & \text{max} & \text{T*} \\
 & \text{1} \leq j \leq k
 \end{array}$$

where $c_6(0 \le c_6 \le 1)$ is determined so as to satisfy the basic probability requirement.

Using the fact that if $F \leq G$ and F(0) = G(0) = 0 then $F_{\alpha} \leq G_{\alpha}$ for $\alpha \geq 1$, where F_{α} is the c.d.f. of X^{α} , F(x) is the c.d.f. of X, G_{α} is the c.d.f. of Y^{α} and G(y) is the c.d.f. of Y. Also, $G_{\alpha}^{-1}F_{\alpha}(X_{1,n}^{\alpha})$ is stochastically equivalent to the i^{th} order statistic from $G^*(x) = 1 - e^{-x}$, for $x \geq 0$, where $X_{1,n} \leq \cdots \leq X_{n,n}$ are order statistics from F. In a manner similar to the proof of Theorem 2.1, one can prove the following theorem.

Theorem 2.5. If $F_i(x) \ge F_{[k]}(x) \ \forall x$ and $i=1,\ldots,k$, $F_{[k]}(0)=0$, $F_{[k]} \le G$, $G(x)=1-e^{-\lambda x^{\alpha}}$, x>0, $\lambda>0$ and $\alpha(\ge 1)$ is known and $n\ge \max\{r,\frac{r-1}{1-c_6}\}$, then

(2.47)
$$\inf_{\Omega} P[CS|R_6] = \int_{0}^{\infty} H^{k-1}(\frac{x}{c_6}) dH(x)$$

where H(x) is the c.d.f. of a χ^2 random variable with 2r d.f.

(D) Selection with respect to the means for Gamma populations

Let π_1, \dots, π_k be k populations with densities

$$f_i(x) = \frac{\beta^{\alpha_i}}{\Gamma(\alpha_i)} x^{\alpha_i-1} e^{-\beta x}$$
, $x \ge 0$, $\beta > 0$, $\alpha_i \ge 1$, $i = 1, \dots, k$.

Let $F_{i}(x)$ be the distribution function of π_{i} , $i=1,\ldots,k$. We are given

a sample size of n from each π_i . Let T_i^* be total life statistic until r^{th} failure from π_i . Let $\alpha_{[1]} \leq \cdots \leq \alpha_{[k]}$ be the ordered values of α_i 's. We are interested in selecting the population with the largest value $\alpha_{[k]}$ (unknown). Since the mean of π_i is $\frac{\alpha_i}{\beta}$, selection of the population with largest mean is equivalent to selecting the population with largest value, $\alpha_{[k]}$. The subset selection rule based on T_i is:

 R_7 : Select population π_i if and only if

where $c_7(0 < c_7 < 1)$ is the largest value chosen to satisfy $P[CS | R_7] \ge P^*$. Since the rule R_7 is scale invariant, we can assume $\beta = 1$.

Case 1: All α_i are unknown and ≥ 1 . Let $\Omega_1 = \{\underline{\alpha} = (\alpha_1, \dots, \alpha_k) : \alpha_i \geq 1 \ \forall i \}$. In this case, by Corollary 2.1 and $F_i \leq G(x) = 1 - e^{-x}$, $x \geq 0$, $i = 1, \dots, k$ we have the following result. If $n \geq \max\{r, \frac{r-1}{1-c_7}\}$, then $\inf_{\Omega} P[CS|R_7] = \int_{0}^{\infty} H^{k-1}(\frac{x}{c_7}) dH(x)$, where H(x) is the c.d.f. of a χ^2 r.v. with 2r d.f.

Case 2: α_i are unknown but assume $1 \leq \alpha_i \leq \Delta$, $i=1,\ldots,k$ and Δ is known. Let $F_{\Delta}(x)$ be the c.d.f. of X with density function $f_{\Delta}(x) = \frac{1}{F(\Delta)} x^{\Delta-1} e^{-x}$, x>0. Let H(x) be the c.d.f. of a χ^2 r.v. with 2r d.f. and let h(x) be its density function. The following theorem is the lower bound for the probability of correct selection without any condition on n.

Theorem 2.6.

(2.49)
$$P[CS|R_7] \ge \int_0^\infty H^{k-1}(\frac{2n}{c_7} x) \frac{2nh(2ny)}{f_{\Delta}(y)} e^{-x} dx$$
where
$$y = F_{\Delta}^{-1}(1 - e^{-x})'.$$

Proof.
$$P[CS | R_7] = P[T^*(k) \ge c 7 \max_{1 \le j \le k-1} T^*(j)],$$

where $T_{(i)}^*$ is associated with $\alpha_{[\,i\,]}$, $i=1,\dots,k$. Since $F_{\bigwedge}(x)\leq F_{_i}(x)\leq G(x)=1-e^{-x}$,

(2.50)
$$P[CS|R_{7}] \ge P[T_{k}^{**} \ge c_{7} \max_{1 \le j \le k-1} T_{j}^{**}]$$

where T_k^{**} is the total life statistic until r^{th} failure from G(x) and $T_j^{**}(j=1,\ldots,k-1)$ is the total life statistic until r^{th} failure from $F_{\Delta}(x)$. Since $\Delta \geq 1$ then $F_{\Delta} \stackrel{<}{_{C}} G$. Let $\phi(x) = G^{-1}F_{\Lambda}(x)$

(2.51)
$$P[T_k^{**} \ge c_7 \quad T_j^{**}, j=1,...,k-1] = P[\phi(\frac{1}{n} \quad T_k^{**}) \ge \phi(\frac{c_7}{n} \quad T_j^{**}) \quad j=1,...,k-1]$$

By Lemma 4.1 of Barlow and Proschan [5] with $a_1=\dots=a_{r-1}=c_7/n$, $a_r=(n-r+1)c_7/n$, $a_i=0$ for $i\geq r+1$ and $\phi(X)=Y$ where X(Y) is a r.v. with distribution function $F_{\Delta}(G)$ respectively, we have

$$(2.52) \quad P[\phi(\frac{1}{n} \ T_k^{**}) \ge \phi(\frac{c_7}{n} \ T_j^{**}) \ , \ j=1,\ldots,k-1] \ge P[\phi(\frac{1}{n} \ T_k^{**}) \ge \frac{c_7}{2n} \ Y_j \ , \ j=1,\ldots,k-1]$$

where Y_j (j=1,...,k-1) is a r.v. with χ^2 with 2r d.f. From (2.50), (2.51) and (2.52), we have

$$P[CS|R_7] \ge \int_0^\infty H^{k-1}(\frac{2n}{c_7} x) dB(x)$$
, where $B(x) = P[\phi(\frac{1}{n} T_k^{**}) \le x]$

Since $B(x) = H[2n F_{\Lambda}^{-1}(1 - e^{-x})]$, then

$$\int_{0}^{\infty} H^{k-1}(\frac{2n}{c_{7}} x) dB(x) = \int_{0}^{\infty} H^{k-1}(\frac{2n}{c_{7}} x) \frac{2nh(2ny)}{f_{\Lambda}(y)} e^{-x} dx.$$

This completes the proof.

Let S denote the size of the selected subset. The expected value of S when $\ensuremath{\text{R}}_7$ is used is given by

(2.53)
$$E(S|R_7) = \sum_{i=1}^{k} P[T_i^* \ge c_7 \max_{1 \le j \le k} T_j^*] .$$

Let $\Omega' = \{\underline{\alpha} = (\alpha_1, \dots, \alpha_k) : 1 \le \alpha_i \le \Delta$, $i = 1, \dots, k\}$. For $\underline{\alpha} \in \Omega'$, since $F_{\underline{\Delta}}(x) \le F_i(x) \le G(x) = 1 - e^{-x}$, then

$$E(S | R_7) \le k P[T_1^{**} \ge c_7 \max_{2 \le j \le k} T_j^{**}]$$

where T_1^{**} is the total life statistic until r^{th} failure from $F_{\Delta}(x)$ and $T_j^{**}(j=2,\ldots,k)$ is the total life statistic until r^{th} failure from G(x).

Thus

(2.54)
$$\sup_{\Omega^{\bullet}} E(S|R_{7}) = k \int_{0}^{\infty} H^{k-1}(\frac{2x}{c_{7}}) dS(x)$$

where H(x) is the c.d.f. of χ^2 r.v. with 2r d.f. and S(x) is the c.d.f. of the total life statistic until rth failure from $F_{\Lambda}(X)$.

- Remark 2.2. (i) We can show that the lower bound for case 2 in Theorem 2.6 is less than or equal to the lower bound for case 1.
- (ii) Now we are dealing with the problem in case 2. Let $\int\limits_0^\infty H^{k-1}(\frac{x}{c_7}) dH(x) = P^* \text{ , then } c_7 \text{ can be determined. If } n \geq \max\{r, (r-1)/(1-c_7)\} \text{ , then we should use the lower bound for case 1. If } r \leq n < (r-1)/(1-c_7) \text{ , then the lower bound for case 1 cannot be applied. In this case, we can use the lower bound for case 2.}$
- (iii) Sometimes, the distribution function S(x) which is defined above the remark 2.2 is hard to compute. From $E(S | R_7) \le k P[T_1^{**} \ge c_7 T_j^{**}, j=2,...,k]$

where T_1^{**} is the total life statistic until r^{th} failure from F_{Δ} and $T_j^{**}(j=2,\ldots,k)$ is the total life statistic until r^{th} failure from G(x). Using the similar arguments in the proof of Theorem 2.6, we can get

$$E(S|R_7) \le k \int_0^\infty H^{k-1} \left[\frac{2n}{c_7} F_{\Delta}^{-1} \left(1 - e^{-\frac{x}{2n}} \right) \right] dH(x)$$

where H(x) is the c.d.f. of a χ^2 r.v. with 2r d.f. In this case, the upper bound of $E(S|R_7)$ can be computed.

Selecting a best population - using indifference zone approach.

Let π_1,\dots,π_k be k populations. The random variable X_i associated with π_i has an absolutely continuous distribution F_i . We assume there exists a $F_{[k]}(x)$ such that $F_{[i]}(x) \geq F_{[k]}(\frac{x}{\delta})$ for all x, $i=1,\dots,k-1$ and $\delta(0<\delta<1)$ is specified. Let

$$(3.1) \quad \Omega(\delta) = \{\underline{F} = (F_1, \dots, F_k) : \exists \text{ a.j. such that } F_i(x) \ge F_i(\frac{x}{\delta}) \ \forall i \ne j \} .$$

The correct selection is the choice of any population which is associated with $F_{[k]}$. We propose the selection rule R_8 : Select population π_i if and only if

(3.2)
$$T_{i} = \max_{1 \le i \le k} T_{j} \text{ where } T_{i} \text{ is defined as in (2.5).}$$

We want the P[CS|R_8] \geq P* , for all $\underline{F} \in \Omega(\delta)$, where P* is specified.

Theorem 3.1. If F_i , $G \in F$, $i=1,\ldots,k$, $F_{[k]} \subset G$, $a_j \ge 0$, $j=1,\ldots,r$, $g(0) \le 1$ and $a_r \ge \delta$, then

(3.3)
$$\inf_{\Omega(\delta)} P[CS|R_8] = \int_{0}^{\infty} G^{k-1} \left(\frac{x}{\delta}\right) dG_T(x)$$

where $G_T(x)$ is the c.d.f. of T.

Proof.
$$P[CS|R_8] = P[T_{(k)} \ge \max_{1 \le j \le k} T_{(j)}].$$

Since $F_{[i]}(\delta x) \ge F_{[k]}(x)$, $i=1,\ldots,k-1$ and by Lemma 2.1, then

$$P[CS|R_8] = P[T_{(k)} \ge \delta \frac{T_{(j)}}{\delta} \forall j \ne k] \ge P[T_{(k)} \ge \delta T_j^* \forall j \ne k]$$

where T_1^*, \dots, T_{k-1}^* , $T_{(k)}$ are i.i.d. with c.d.f. $W_k(x)$. Using the same argument as in Theorem 2.1, we have our theorem.

For given k,δ , P* and G(x), we can possibly find the values of the pair (n,r), $(n\geq r)$ which satisfy

(3.4)
$$a_r \ge \delta \quad \text{and} \quad \int_0^\infty G^{k-1} \left(\frac{x}{\delta}\right) dG_T(x) \ge P^* .$$

If G(x) = x for 0 < x < 1, we can always find the values of the pair (n,r), $(n \ge r)$ which satisfy

$$n \begin{pmatrix} n-1 \\ r-1 \end{pmatrix} \int_{0}^{\infty} \begin{bmatrix} n & \binom{n}{i} \binom{x}{\delta} & \binom{1-\frac{x}{\delta}}{\delta} \end{bmatrix}^{i} \left(1-\frac{x}{\delta}\right)^{n-i} dx \geq p*$$

If $G(x)=1-e^{-x}$ for $x\geq 0$, we can find the smallest integer r, say r_0 , which satisfies $\int\limits_0^\infty H^{k-1}(\frac{x}{\delta})dH(x)\geq P^* \text{ where } H(x) \text{ is the c.d.f. of a}$ χ^2 random variable with 2r d.f. Since $\frac{1}{\delta} a_r \geq 1 \text{ iff } n \geq \frac{r-1}{1-\delta} \text{ , we can}$ find the minimum n satisfying $n\geq \max\{r_0,(r_0-1)/(1-\delta)\}$.

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Selection Procedures, Reliability,	Convex, Star-sl	haped, IFR, IFRA,

In this paper we are interested in studying multiple decision procedure for $k(k \ge 2)$ populations which are themselves unknown but which one assumed to belong to a restricted family. We propose to study a selection procedure for distributions associated with these populations which are convex-ordered with

respect to a specified distribution G assuming there exists a best one. The

procedure described here is based on a statistic $T_i = \sum_{j=1}^{n} a_j X_{i,j,n}$ for

 $i=1,\ldots,k$ where $X_{i;j,n}$ is the j-th order statistic from F_i , r is a fixed positive integer $(1 \le r \le n)$, $a_j = gG^{-1}(\frac{j-1}{n}) - gG^{-1}(\frac{j}{n})$ for $j=1,\ldots,r-1$, $a_r = gG^{-1}(\frac{r-1}{n})$ and g is the density of G. This statistic T_i was considered by Barlow and Doksum (1972). If $G(x) = 1 - e^{-x}$ for x > 0, then $nT_i = X_{i;1,n} + \dots + X_{i;r-1,n} + (n-r+1)X_{i;r,n}$ is the total life statistic until r-th failure from F_i . This shows that the procedure based on T_i generalizes Patel's result (1976) for the IFR family.

The infimum of the probability of a correct selection is obtained and the asymptotic expression is also obtained using the subset selection approach. Some other properties of this procedure are discussed. We also study the asymptotic relative efficiencies of this rule with respect to some selection procedures proposed by Barlow and Gupta (1969) for the star-shaped ordered distributions, Gupta (1963) for the gamma populations with unknown shape parameters and etc. An example is given to illustrate the use of the selection procedure for the two independent uniform distributions. Application to quantile selection rules for distributions convex ordered with respect to Weibull distribution is given. A selection procedure for selecting the best population using the indifference zone approach is also studied.