

On the Stochastic Integrals of Gaussian Processes and  
Local Times

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ABSTRACT

Let  $X_t$ ,  $0 \leq t \leq T$  be a Gaussian process and let  $L(x)$  be the local time of  $X_t$  (occupation time density with respect to the clock  $d\langle X, X \rangle_t$ ) up to time  $T$  at  $x$ . Then

$$\int_0^T g(X_t) dX_t = \int_{X_0}^{X_T} g(y) dy - \frac{1}{2} \int_{-\infty}^{\infty} L(x) dg(x)$$

under certain conditions.

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1. Introduction. The direct connection between the stochastic integrals of a process  $X_t$  and its local time  $L_t(x)$  is the Tanaka's formula

$$(1.1) \quad (X_t - x)^+ = (X_0 - x)^+ + \int_0^t 1_{[x, \infty)}(X_s) dX_s + \frac{1}{2} L_t(x).$$

The local time  $L_t(x)$  satisfies

$$(1.2) \quad L_t(x) = \lim_{n \rightarrow \infty} \sum_{i=0}^{n-1} \int_0^t 1_{[x, x + \frac{1}{n})}(X_s) d\langle X, X \rangle_s$$

where  $\langle X, X \rangle_s$  is the quadratic variation of  $X_t$  over  $[0, s]$ . That is

$$(1.3) \quad \langle X, X \rangle_s = \lim \sum_i (X_{s_{i+1}} - X_{s_i})^2$$

along any sequence of partitions  $\{s_0=0 < s_1 < \dots < s_n=s\}$  whose mesh goes to 0 sufficiently fast. The meaning of (1.2) is that  $L_t(x)$  is the occupation time density relative to the clock  $d\langle X, X \rangle_s$  up to time  $t$  at  $x$ . In the case that  $X_t$  is a standard Wiener process (see [6, p. 101]), then  $\langle X, X \rangle_s = s$ . If  $X_t$  is a continuous semimartingale, then  $\langle X, X \rangle_s = \langle X^c, X^c \rangle_s$  where  $X^c$  is the local martingale part of  $X$  in the Doob-Meyer decomposition. If  $X_t$  is not continuous, then the above result needs some modification (see [7, p. 32]). The purpose of this note is to show that the above result is also good for a Gaussian process whose covariance function satisfies certain conditions.

2. Integration. Let  $X_t$ ,  $0 \leq t \leq T$ , be a zero mean Gaussian process. We need to define

the stochastic integral of the type  $\int_0^T g(X_t) dX_t$ , where  $g$  is a Borel function. The

stochastic integral of a Gaussian process was defined in [4] through the tensor product of some Hilbert space. A Riemann-Stieltjes type of integration was given

in [5]. We shall use the latter.

Let the covariance function  $R(s,t)$  of  $X_t$  satisfy the following conditions:

(2.1)  $R(s,t)$  is continuous in  $(s,t)$  and has continuous first partial derivatives in  $\{(s,t): 0 \leq s \leq t \leq T\}$ .

(2.2) There exists a constant  $C > 0$  such that, for  $s \neq t$ ,  $|R(s+ds, t+dt) - R(s+ds, t) - R(s, t+dt) + R(s, t)| \leq C|dsdt|$ .

Then the quadratic variation  $\langle X, X \rangle_t$  exists and equals to (see [1])

$$(2.3) \quad \langle X, X \rangle_t = \int_0^t f(s) ds$$

where  $f(t)$  is a nonnegative continuous function of  $t$  which is obtained by

$$(2.4) \quad f(t) = \lim_{h \rightarrow 0^+} \frac{1}{h} \{2R(t, t) - R(t, t-h) - R(t, t+h)\}.$$

Let  $bC^1$  denote the space of all differentiable functions on  $R$  which have bounded derivatives. If  $g \in bC^1$ , then see ([5, Thm 3.1, p. 623]).

$$(2.5) \quad \int_0^T g(X_t) dX_t = \lim \sum_i g(X_{t_i}) (X_{t_{i+1}} - X_{t_i})$$

exists along any sequence of partitions  $\{t_0=0 < t_1 < \dots < t_n=T\}$  whose mesh goes to 0. Furthermore, it is equal to

$$(2.6) \quad \int_0^T g(X_t) dX_t = \int_{X_0}^{X_T} g(y) dy - \frac{1}{2} \int_0^T g'(X_t) d\langle X, X \rangle_t$$

where  $\langle X, X \rangle_t$  is given by (2.3). However, if  $g \notin bC^1$ , then, unlike the martingales case which have orthogonal increments, it is difficult to show the existence of (2.5) in general. We shall seek an alternative definition through (2.6).

Let  $\Phi$  denote the space of all infinitely differentiable probability density

functions with compact support. For each Borel function  $h$  and  $\varphi \in \Phi$ , let

$$(2.7) \quad (h * \varphi)_m(x) = m \int_{-\infty}^{\infty} h(x-y) \varphi(my) dy = m \int_{-\infty}^{\infty} h(y) \varphi(mx-my) dy, \quad m \geq 1.$$

Definition 2.1. Let  $g$  be a Borel function which is integrable over any finite interval. If there exists a r.v.  $Y_g$  such that

$$(2.8) \quad Y_g = \lim_{m \rightarrow \infty} \int_0^T (g * \varphi)_m'(X_t) f(t) dt$$

in some sense for all  $\varphi \in \Phi$ , then we define

$$(2.9) \quad \int_0^T g(X_t) dX_t = \int_{X_0}^{X_T} g(y) dy - \frac{1}{2} Y_g.$$

Remark 22. It is clear from (2.7) and (2.8) that if  $g \in bC^1$ , then

$Y_g = \int_0^T g'(X_t) f(t) dt$ . Hence (2.9) becomes (2.6). Therefore, Definition 2.1 is an extension of (2.5).

3. Formulas. Let us now derive some relations between the stochastic integrals of  $X_t$  and the local time  $L_t(x)$ . First we note that conditions (2.1) and (2.2) imply that

$$(3.1) \quad E|X_t - X_s|^2 = f(t) |t-s| + o(t-s)$$

for small  $|t-s|$ . Hence,  $E|X_t - X_s|^4 \geq C(t-s)^2$ ,  $0 \leq t, s \leq T$ , for some constant

$C$ . It is well known that this inequality implies that the process  $X_t$  is equivalent to a process whose sample paths are continuous with probability 1.

Therefore, we can assume that  $X_t$  has continuous sample paths with probability 1.

From (3.1), we see that

$$\int_0^T \int_0^T \left\{ E |X_t - X_s|^2 \right\}^{-\frac{1}{2}} f(t) f(s) dt ds .$$

Then (see [2, Lemma 5.1, p. 276]) the nonnegative monotone increasing process

$$v(x) = \int_0^T 1_{(-\infty, x)}(X_s) f(s) ds$$

is absolutely continuous w.r.t. the Lebesgue measure

with probability 1. Its Radon-Nikodym derivative  $L(x)$  ( $=L_T(x)$ ) exists a.s. and belongs to  $\mathcal{L}^2(\mathbb{R})$ .  $L(x)$  is the local time of  $X_t$  up to time  $T$  at  $x$ .

Lemma 3.1. Let  $g$  be a continuous monotone function. If  $\int_{-\infty}^{\infty} L(x) dg(x)$  exists,

then  $\int_0^T g(X_t) dX_t$  exists. Furthermore,

$$(3.2) \quad \int_0^T g(X_t) dX_t = \int_{X_0}^{X_T} g(y) dy - \frac{1}{2} \int_{-\infty}^{\infty} L(x) dg(x) \quad \text{a.s.}$$

Proof. Let  $\varphi \in \Phi_m$ . Then  $(g^*\varphi)'_m(x)$  is a continuous function. Hence (see [2, (1.2), p. 270])

$$(3.3) \quad \begin{aligned} \int_0^T (g^*\varphi)'_m(X_t) f(t) dt &= \int_{-\infty}^{\infty} (g^*\varphi)'_m(x) L(x) dx \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} m^2 g(y) \varphi'(mx-my) dy L(x) dx \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} m \varphi(mx-mg) L(x) dg(y) dx = I_m. \end{aligned}$$

Since  $X_t$  is continuous,  $L(x)$  vanishes outside the range of  $X_t$ , and hence  $L(x)$  vanishes outside some compact set. This fact together with the fact that  $\varphi$  has compact support implies that the integrand in the last integral of (3.3) has compact support in  $\mathbb{R}^2$ . Therefore, Fubini's Theorem applies. We have

$$\begin{aligned}
 I_m &= \int_{-\infty}^{\infty} \left\{ \int_{-\infty}^{\infty} m\varphi(mx-my) L(x) dx \right\} dg(y) \\
 (3.4) \quad &= \int_{-\infty}^{\infty} \left\{ \int_{-\infty}^{\infty} m\varphi(mx) L(x+y) dx \right\} dg(y)
 \end{aligned}$$

Let the support of  $\varphi$  be contained in  $[-K, K]$ . Then the integral in the brace of the last term of (3.4) is an average of  $L$ , which belongs to  $L^2(\mathbb{R})$ , over  $[y - \frac{K}{m}, y + \frac{K}{m}]$ . Therefore it converges to  $L(y)$  for a.e.  $y$ . This fact plus the existence of  $\int_{-\infty}^{\infty} L(y) dg(y)$  and the continuity of  $g$  imply that

$$(3.5) \quad Y_g = \lim_{m \rightarrow \infty} I_m = \int_{-\infty}^{\infty} L(y) dg(y)$$

exists for all  $\varphi \in \Phi$ . Lemma 3.1 then follows from the Definition 2.1, (2.9) and (3.5).

If  $g$  is not continuous, we see from the above proof that we need also the condition

$$(3.6) \quad L(x) = \lim_{m \rightarrow \infty} m \int_{-\infty}^{\infty} L(x+y) \varphi(my) dy,$$

for  $\varphi \in \Phi$  and  $x$  where  $g(x+) \neq g(x-)$ , to get (3.5). Therefore, Lemma 3.1 will hold if the additional condition (3.6) is satisfied. We can apply the same argument to  $g$  which is of bounded variation over finite intervals.

Theorem 3.2. Let  $g$  be a real function which is of bounded variation over any finite interval. If  $\int_{-\infty}^{\infty} L(x) dg(x)$  exists and the condition (3.6) is satisfied,

then  $\int_0^T g(X_t) dX_t$  exists and the identity (3.2) holds.

By letting  $g(y) = 1_{[x, \infty)}(y)$ , and noticing that (3.6) is satisfied for a.e.  $x \in \mathbb{R}$ , we obtain the following Tanak's formula.

Corollary 3.3. For a.e.  $x \in \mathbb{R}$ , and a.s.

$$(X_t - x)^+ = (X_0 - x)^+ + \int_0^T 1_{[x, \infty)}(X_t) dX_t + \frac{1}{2} L(x).$$

Remark 3.4. There are conditions (see [3, pp. 52-53]) such that  $L(x)$  is continuously differentiable in  $x$ . Then

$$(3.7) \quad \int_{-\infty}^{\infty} L(x) dg(x) = \int_{-\infty}^{\infty} g(x) dL(x).$$

However, these known conditions are incompatible to the condition (2.1). It remains the possibility to find a condition such that  $L(x)$  is absolutely continuous w.r.t. the Lebesgue measure. Then (3.7) can be discussed for Borel measurable function  $g$ . And so can

$$\int_0^T g(X_t) dX_t = \int_{X_0}^{X_T} g(y) dy - \frac{1}{2} \int_{-\infty}^{\infty} g(x) dL(x).$$



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