

OPTIMAL SELECTION OF SINGLE ARRAYS  
FOR PARAMETER DESIGN EXPERIMENTS

by

C.F.J. Wu                      and              Y. Zhu  
University of Michigan              Purdue University

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Department of Statistics  
Purdue University  
West Lafayette, IN USA

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C. F. J. Wu

Department of Statistics and of  
Industrial and Operations Engineering  
University of Michigan,  
Ann Arbor, MI 48109-1285  
(jeffwu@umich.edu)

Y. Zhu

Department of Statistics  
Purdue University  
West Lafayette, IN 47907-1399  
(yuzhu@stat.purdue.edu)

## Abstract

An outstanding issue in robust parameter design is the choice of experimental plans. Single arrays were proposed as an alternative to the inner-outer arrays advocated by Taguchi. Because factorial effects in parameter design experiments have properties distinctly different from those in traditional fractional factorial experiments, new principles on the relative importance of effects need to be considered. Based on them a new criterion is developed to discriminate among different single arrays. Search algorithms are developed and used to construct “optimal” single arrays with run size 8, 16, 32 and 64.

KEY WORDS: fractional factorial design, effect ordering principle, minimum  $J$ -aberration criterion

## 1 INTRODUCTION

Robust parameter design (or briefly parameter design) is an important method for variation reduction in industrial processes and products. The quality of a system (a product or a process) is mainly affected by two types of factors which are control factors and noise factors. *Control factors* are the variables whose values can be adjusted but remain fixed once they are chosen. *Noise factors* are the variables which are hard to control in a system’s normal production and use environments. When a parameter design experiment is conducted, both the control factors and noise factors are varied systematically. The basic idea of parameter design is to explore the effects of control factors, noise factors and their interactions on the performance of a system, and to exploit these effects, by choosing optimal control factor settings, to bring the system mean response on target and reduce the performance variation due to noise factors. For a

comprehensive review, see Chapters 10 and 11 of Wu and Hamada (2000).

### 1.1 Cross Arrays, Single Arrays and Modeling Techniques

Taguchi (1986) proposed to use cross arrays (or *inner-outer arrays* in his terminology) for parameter design experiments. Two separate arrays are generated for control factors and noise factors. They are called the control array (denoted by CA) and the noise array (denoted by NA) respectively. A *cross array* consists of all the combinations of the settings of CA and the settings of NA. Suppose CA and NA have run size  $m_1$  and  $m_2$  correspondingly. Then the run size of the cross array is  $m_1 m_2$ . Let  $y_{i,j}$  be the response for the combination of the  $i^{th}$  control setting and the  $j^{th}$  noise setting. At any fixed control setting  $i$ , there are  $m_2$  responses,  $\{y_{i,j}\}_{1 \leq j \leq m_2}$  across NA. The sample mean and sample variance,  $\bar{y}_i = \frac{1}{m_2} \sum_{j=1}^{m_2} y_{i,j}$  and  $s_i^2 = \frac{1}{m_2-1} \sum_{j=1}^{m_2} (y_{i,j} - \bar{y}_i)^2$ , are the summary statistics for the  $i^{th}$  control setting. Row-summary modeling approach is to model these summary statistics or some functions based on them in terms of the control factors. Two examples are signal-to-noise ratio modeling and location-dispersion modeling (Myers and Montgomery, 1995; Wu and Hamada, 2000).

When the number of factors is large, cross arrays become costly. Single arrays proposed by Welch et al. (1990) and Shoemaker et al. (1991), are an economical alternative to cross arrays. Instead of using two arrays, a *single array* is employed with some of its columns assigned to control factors and others to noise factors. With the crossing structure ignored, a cross array can be viewed as a special case of a single array.

In the row-summary modeling approach, the responses across the noise array for any fixed control setting are considered as the noise replicates. The response  $y$ , in fact, can be modeled as a function of control and noise factors (Vining and Myers, 1990; Welch et al., 1990; Shoemaker et al., 1991). This approach is called the response modeling approach and the fitted model  $\hat{y}$  the response model. Based on  $\hat{y}$ , the mean and variance of the response can also be estimated, so that a two-step procedure can be employed for parameter design optimization. Unlike the row-summary modeling, it is especially suitable for single arrays. It provides flexibility to accommodate effects with different degrees of importance.

The problem of selecting optimal single arrays has not been properly addressed in the literature. Our idea, primarily motivated by Shoemaker et al. (1991) and Wu and Hamada (2000), is to consider all possible general single arrays, investigate their estimation capacity for the purpose of parameter design and select optimal arrays according to some overall criteria.

## 1.2 Other Experimental Plans for Parameter Design

An interesting extension of cross array is the compound orthogonal array proposed by Rosenbaum (1994, 1996). Let  $OA(N, k, 2, t)$  denote a 2-level orthogonal array with  $N$  rows,  $k$  columns and strength  $t$  (Rao, 1947). A *compound orthogonal array* with parameters  $N_1, N_2, k_1, k_2, t_1$  and  $t_2$  is an  $N_1 N_2 \otimes (k_1 + k_2)$  orthogonal array with the following structure: the first  $k_1$  columns form  $N_2$  identical copies of an  $OA(N_1, k_1, 2, t_1)$ , and for each fixed setting of the first  $k_1$  columns, the corresponding settings for the remaining  $k_2$  columns form an  $OA(N_2, k_2, 2, t_2)$ . If the first  $k_1$  columns are assigned to control factors and the remaining  $k_2$  columns to noise factors, it is said that the strength among the control factors is  $t_1$  and the strength for the noise factors is  $t_2$ . The strength of the whole compound array is denoted by  $t_3$ . The values of  $t_1, t_2$  and  $t_3$  should be as large as possible for given  $N_1, N_2, k_1$  and  $k_2$ . Based on fractional factorial plans, Hedayat and Stufken (1999) constructed optimal compound orthogonal arrays in terms of  $t_1, t_2$ , and  $t_3$ . In general, an orthogonal array with strength  $t \geq 1$  is a compound orthogonal array for some set of parameters, so is any fractional factorial design.

In order to estimate all main effects, control-by-control interactions and control-by-noise interactions, Borkowski and Lucas (1997) and Box and Jones (1993) suggested using designs with mixed-resolutions. A mixed-resolution design is a second-order design for control effects and control-by-noise interactions.

## 1.3 Basics of Two-Level Fractional Factorial Designs

Suppose there are  $l$  factors in an experiment. The factors are denoted by  $1, 2, \dots, l$ , which are called *letters* in design theory. The generalized interaction among factors  $i_1, i_2, \dots$ , and  $i_k$  is denoted by  $i_1 i_2 \dots i_k$ , which is called a *word*. The generalized interactions are also called factorial effects. A  $2^{l-p}$  fractional factorial design, which has  $2^r$  runs with  $r = l - p$ , is determined by  $r$  independent factors and  $p$  independent defining words. The *defining contrast subgroup*  $\mathcal{G}$  consists of all possible combinations of the independent defining words. For two fractional factorial designs  $d_1$  and  $d_2$ , if  $d_2$  can be derived from  $d_1$  by relabeling letters and/or changing signs,  $d_1$  and  $d_2$  are said to be *isomorphic*. The number of letters in a word is the *wordlength*, and the vector  $W = (A_1, A_2, \dots, A_l)$  is called the *wordlength pattern*, where  $A_i$  denotes the number of words of length  $i$  in  $\mathcal{G}$ . *Resolution* is defined as the smallest  $r$  such that  $A_r \geq 1$ . For two designs  $d_1$  and  $d_2$ ,  $d_1$  is said to have less aberration than  $d_2$  if  $A_{i_0}(d_1) < A_{i_0}(d_2)$ , where  $i_0$  is the smallest value such that  $A_{i_0}(d_1) \neq A_{i_0}(d_2)$ . If there is no design with less aberration than

$d_1$ , then  $d_1$  is said to have *minimum aberration* (Fries and Hunter, 1980).

Clear effects and eligible effects (Wu and Chen, 1992) are another two important concepts. A main effect or a two-factor interaction (henceforth abbreviated as *2fi*) is *clear* if it is not aliased with any other main effects or *2fi*'s, and is *eligible* if it is not clear but only aliased with some other *2fi*. The *number of clear effects* can be used as a supplementary criterion to minimum aberration

The paper is organized as follows. In Section 2, single arrays are formally defined, their basic structure and property discussed, and several examples given. In Section 3, a new principle about factorial effects in parameter design is proposed. In Section 4, several criteria for selecting optimal single arrays are proposed. A construction method of single arrays is presented in Section 5. In Section 6, various single arrays with small run size are discussed in details. Good single arrays with run size 8, 16, 32 and 64 are included in Appendices D.1-D.4.

## 2 GENERAL SINGLE ARRAYS: CONSTRUCTION AND PROPERTIES

For consistency, control factors are denoted by capital letters  $A, B, C$ , etc.; noise factors by lower case letters  $a, b, c$ , etc. The letters  $C$  and  $n$  are used generically to represent a control factor and a noise factor respectively.

Suppose there are  $k_C$  control factors and  $k_n$  noise factors, each at two levels. A general single array is a  $2^{l-p}$  fractional factorial design with  $k_C$  columns assigned to the control factors and  $k_n$  columns assigned to the noise factors, where  $l = k_C + k_n$ , and  $p$  is the fraction index. Single arrays do not require any *a priori* structures such as “crossing” in cross arrays. For a given run size, cross arrays and compound orthogonal arrays may not exist for certain number of control factors and of noise factors.

**Lemma 1** The smallest cross array for  $k_C$  control factors and  $k_n$  noise factors requires  $2^{\lceil \log_2(k_C+1) \rceil + \lceil \log_2(k_n+1) \rceil}$  runs, where  $\lceil x \rceil$  denotes the smallest integer greater than or equal to  $x$ .

*Proof:* Suppose the run size of CA is  $m_1 = 2^{n_1}$ . A necessary and sufficient condition that the CA can accommodate  $k_C$  control factors is  $2^{n_1} - 1 \geq k_C$ , i.e.,  $n_1 \geq \log_2(k_C+1)$ , or  $n_1 \geq \lceil \log_2(k_C+1) \rceil$ . Therefore, the smallest CA has run size  $2^{\lceil \log_2(k_C+1) \rceil}$ . Similarly, the smallest NA has run size  $2^{\lceil \log_2(k_n+1) \rceil}$ . The lemma follows by taking the product of these two numbers.

For convenience,  $S(k_C, k_n, p)$  is used to denote a single array with  $k_C$  control factors,  $k_n$  noise factors and  $2^{(k_C+k_n)-p}$  runs. Suppose  $S_1$  and  $S_2$  are two single arrays. If  $S_1$  can be derived

from  $S_2$  by the relabeling of control factors, of noise factors, or by change of signs,  $S_1$  and  $S_2$  are said to be *isomorphic*. If the control and noise factors are not distinguished, a single array becomes an ordinary fractional factorial plan. This fractional factorial plan is called the *basic frame* of the single array. Since control and noise factors play different roles in parameter design, different ways to assign the columns of a basic frame to control and noise factors can generate non-isomorphic single arrays. The distinction between control and noise factors also induces a partition of the columns of the basic frame into two subgroups. The columns assigned to the control factors are called the *control columns* and those to the noise factors the *noise columns*. Hence a single array is determined by its basic frame and the column partition. Obviously, if two single arrays have non-isomorphic basic frames, they are non-isomorphic.

In the following, the single array  $S(3, 3, 2)$  is used to illustrate the structure and properties of single arrays. The three control factors are denoted by  $A$ ,  $B$  and  $C$ , and the three noise factors by  $a$ ,  $b$  and  $c$ . There are altogether four nontrivial and non-isomorphic  $2^{6-2}$  basic frames given by the following defining relations (Chen, Sun and Wu, 1993):

$$I = 123 = 1456 = 23456, \quad (1)$$

$$I = 123 = 456 = 123456, \quad (2)$$

$$I = 1234 = 1256 = 3456, \quad (3)$$

and

$$I = 123 = 156 = 2356. \quad (4)$$

According to the minimum aberration criterion, (3) with the wordlength pattern  $W=(0, 0, 0, 3, 0, 0)$  is the best and (4) is the worst with the wordlength pattern  $W=(0, 0, 2, 1, 0, 0)$ . Based on (1), there are six different ways to assign the columns to the control factors and the noise factors. For example, assigning columns 1, 2 and 3 to  $A$ ,  $B$  and  $C$ , and columns 4, 5 and 6 to  $a$ ,  $b$ , and  $c$  produces a single array with the defining relation

$$S_1 : \quad I = ABC = Aabc = BCabc. \quad (5)$$

Assigning 1, 2 and 3 to  $a$ ,  $b$  and  $c$  and 4, 5 and 6 to  $A$ ,  $B$  and  $C$  leads to a different (and non-isomorphic) single array with the defining relation

$$S_2 : \quad I = abc = ABCa = ABCbc. \quad (6)$$

The other single arrays based on (1) are given as follows,

$$S_3 : \quad I = Aab = BCac = ABCbc, \quad (7)$$

$$S_4 : \quad I = ABa = ACbc = BCabc, \quad (8)$$

$$S_5 : \quad I = Aab = ABCc = BCabc, \quad (9)$$

$$S_6 : \quad I = ABa = Cabc = ABCbc. \quad (10)$$

Based on the basic frame (2), there are eight non-isomorphic single arrays. Among them, one is given by

$$S_7 : \quad I = abc = ABC = ABCabc. \quad (11)$$

It is easy to see that  $S_7$  is a  $2^{3-1} \times 2^{3-1}$  cross array. The basic frame (3) is the  $2^{6-2}$  minimum aberration design and generates the following two non-isomorphic single arrays,

$$S_8 : \quad I = ABab = ACac = BCbc, \quad (12)$$

and

$$S_9 : \quad I = ABCa = Aabc = BCbc. \quad (13)$$

Notice that  $S_2$ ,  $S_4$ ,  $S_5$ , and  $S_9$  all have one defining word which consists of some control factors and only one noise factor. This implies that when the setting of the control factors is fixed, the level of the noise factor that appears in the defining word is also fixed. For instance, in  $S_2$ , the defining word  $ABCa$  implies the aliasing of  $a$  with  $ABC$ . If the levels of  $A$ ,  $B$  and  $C$  are chosen, so is  $a$ 's. This implies that the corresponding noise array has strength 0, because the level of the noise factor  $a$  does not vary. Hence,  $S_2$ ,  $S_4$ ,  $S_5$ , and  $S_9$  are not compound orthogonal arrays according to the definition.

Let  $N_C$  denote the number of clear control main effects,  $N_n$  the number of clear noise main effects,  $N_{CC}$  the number of clear control-by-control interactions,  $N_{Cn}$  the number of clear control-by-noise interactions (henceforth abbreviated as  $Cn$  effects), and  $N_{nn}$  the number of clear noise-by-noise interactions. The estimation capacity of single arrays  $S_1$  to  $S_9$  in terms of the numbers of eligible effects and clear effects is summarized in Table 1. Define

$$\alpha = (N_C, N_n, N_{CC}, N_{Cn}, N_{nn}) \quad (14)$$

Table 1: Comparison of Estimation Capacities for  $S_1$  to  $S_9$

Design	Eligible effects	Clear Effects	$N_C$	$N_n$	$N_{CC}$	$N_{Cn}$	$N_{nn}$
$S_1$	$A, B, C, Aa, Ab, Ac, ab, ac, bc$	$a, b, c, Ba, Bb, Bc, Ca, Cb, Cc$	0	3	0	6	0
$S_2$	$a, b, c, AB, AC, BC, Aa, Ba, Ca$	$A, B, C, Ab, Ac, Bb, Bc, Cb, Cc$	3	0	0	6	0
$S_3$	$A, a, b, Ba, Bc, Ca, Cc, BC, ac$	$B, C, c, AB, AC, Ac, Bb, Cb, bc$	2	1	2	3	1
$S_4$	$A, B, a, AC, Ab, Ac, Cb, Cc, b, c$	$C, b, c, BC, Bb, Bc, Ca, ac, bc$	1	2	1	3	2
$S_5$	$A, a, b, AB, AC, BC, Ac, Bc, Cc$	$B, C, c, Ba, Bb, Ca, Cb, ac, bc$	2	1	0	4	2
$S_6$	$A, B, a, Ca, Cb, Cc, ab, ac, bc$	$C, b, c, AC, BC, Ab, Ac, Bb, Bc$	1	2	2	4	0
$S_7$	$A, B, C, a, b, c$	$Aa, Ab, Ac, Ba, Bb, Bc, Ca, Cb, Cc$	0	0	0	9	0
$S_8$	all 2fi's	$A, B, C, a, b, c$	3	3	0	0	0
$S_9$	all 2fi's	$A, B, C, a, b, c$	3	3	0	0	0



for a single array and call it the *clear estimation index vector*. For single arrays with a given basic frame, the total numbers of clear main effects and of clear *2fi*'s are fixed, i.e.,  $N_C + N_n$  and  $N_{CC} + N_{Cn} + N_{nn}$  are constants. But the distribution across  $N_C$ ,  $N_n$ ,  $N_{CC}$ ,  $N_{Cn}$  and  $N_{nn}$  varies. This is transparent by comparing the single arrays  $S_1$  to  $S_6$  which share the basic frame (1). In parameter design,  $C$  and  $Cn$  are most important, because they can be used to adjust the responses on target and to reduce response variation. (More discussion on this is deferred to the next section.) From Table 1,  $S_2$  appears to be the best among  $S_1$  to  $S_6$ . If the experimenters can assume that  $CC$ 's are negligible, then the eligible  $Cn$  effects,  $Aa$ ,  $Ab$  and  $Ac$ , are also estimable.  $S_7$  is a cross array. An important property for cross arrays is that all the  $Cn$  effects can be clearly estimated (see Theorem 10.1 of Wu and Hamada, 2000). So  $S_7$  has all  $Cn$  effects clear, but its main effects are only eligible. If response adjustment is not important,  $S_7$  may be preferred. For  $S_8$  and  $S_9$ , all the main effects are clear, but none of the *2fi*'s are clear. Note that  $S_8$  and  $S_9$  are based on the basic frame (3), which has minimum aberration. Hence minimum aberration designs do not necessarily provide good basic frames for single arrays.

In general, for any fixed  $k_C$ ,  $k_n$  and run size  $N$ , there are many non-isomorphic single arrays. The choice of optimal single arrays is a challenging problem. Standard criteria like maximum resolution and minimum aberration are not suitable for parameter design, because they do not recognize the different roles played by the control and noise factors. Although compound orthogonal array makes a distinction between control and noise factors, its orthogonality requirement rules out some interesting designs such as  $S_2$ ,  $S_4$ ,  $S_5$  and  $S_9$  in the previous example. The strengths  $t_1$ ,  $t_2$  and  $t_3$  are a rough description of the structure and properties of a compound orthogonal array. For example, for both  $S_1$  and  $S_7$ ,  $t_1 = 2$ ,  $t_2 = 2$  and  $t_3 = 2$ , but  $S_1$  and  $S_7$  are still different in terms of aliasing and estimation capacity. Mixed-resolution is another attempt to address this question, but a mixed resolution array requires the length of any defining words involving control factors to be at least 5, and the length of any defining words not involving control factors to be at least 3. This is a strong condition, even stronger than the crossing structure. As a result, the required run size is large. For example, for  $k_C=3$ ,  $k_n = 3$  and  $N = 16$ , no single arrays satisfy the mixed resolution criterion. The smallest mixed resolution array for the case is a 32-run  $2^{6-1}$  plan with  $I=ABCabc$  (Borkowski and Lucas, 1997).

Next, a systematic approach is developed to address this problem. First, a new effect ordering principle is proposed. Based on this principle, optimality criteria will be derived.

### 3 EFFECT ORDERING PRINCIPLE FOR PARAMETER DESIGN

The minimum aberration criterion is based on the hierarchical ordering principle (in abbreviation, HOP): (i) lower order effects are more important than higher order effects, (ii) effects of the same order are equally important. The factorial effects in parameter design have more complicated interpretations than those in ordinary fractional factorial design, because parameter design has two objectives, response mean optimization and variation reduction. If a factorial effect consists of  $i$  control factors and  $j$  noise factors, it is of type  $e_{i,j} = \overbrace{C..C}^i \overbrace{n..n}^j$ . Since control factors are not further distinguished among each other, the hierarchical ordering principle can be applied to control effects, that is, lower-order control effects are more important than higher-order control effects; control effects of the same order are equally important. The same can be said about noise effects. Notice that  $\{e_{i,0}\}_{i \geq 0}$  is the collection of all types of control effects and  $\{e_{0,j}\}_{j \geq 0}$  the collection of all types of noise effects. According to the HOP, control effects and noise effects can be rank-ordered as  $e_{0,0} > e_{0,1} > e_{0,2} > \dots > e_{0,j} > e_{0,j+1} > \dots$ , and  $e_{0,0} > e_{1,0} > e_{2,0} > \dots > e_{i,0} > e_{i+1,0} > \dots$ . It is not appropriate to directly apply the HOP to  $Cn$  effects, because HOP would find the four most important groups of effects to be  $\{C, n\}$ ,  $\{CC, Cn, nn\}$ ,  $\{CCC, CCn, Cnn, nnn\}$  and  $\{CCCC, CCCn, CCnn, Cnnn, nnnn\}$ . In parameter design, the  $Cn$  effects are more likely to be present because engineering knowledge and experience may suggest that the selected noise factors are expected to interact with some control factors. Since  $Cn$  can often be used to achieve robustness without incurring more cost, priority should be given to these interactions so as not to miss any opportunities. Hence,  $C$ ,  $n$  and  $Cn$  should be considered to be equally important, wherein  $C$  is crucial for mean response adjustment, and  $n$  and  $Cn$  are useful for variation reduction. Then the second set consists of  $CC$  and  $nn$ , wherein  $CC$  affects the response mean, and  $nn$  affects the response variation (but its contribution cannot be controlled or changed). Further opportunities for variation reduction appear in the third group which contains  $CCn$  and  $Cnn$ . Because  $Cnn$  involves more noise factors than  $CCn$ ,  $CCn$  is considered to be more important than  $Cnn$ . Following a similar argument, all the factorial effects in parameter design can be rank-ordered. A numerical rule can be used to help define the ranking. In general, if an effect is of type  $e_{i,j}$ , its weight is defined

to be

$$W(e_{i,j}) = \begin{cases} 1 & \text{if } \max(i, j) = 1, \\ i & \text{if } i > j \text{ and } i > 1, \\ j + \frac{1}{2} & \text{if } i \leq j \text{ and } j \geq 2. \end{cases}$$

For any  $w$  in  $\{1, 2, 2.5, 3, 3.5, \dots\}$ ,  $\mathcal{E}_w$  is the set of effects with weight  $w$ . Sometimes,  $\mathcal{E}_w$  can also be viewed as the set of effect types with weight  $w$ . The first seven  $\mathcal{E}_w$ 's are listed in Table 2. The previous discussion can be summarized by the following *Effect Ordering Principle* (in abbreviation, EOP):

- (i). Effects with smaller weight are more important than effects with larger weight.
- (ii). Effects with same weight are equally important.

High order factorial effects are usually insignificant. In practice, the experimenters are seldom

Table 2: Factorial Effects in Parameter Designs Rank-Ordered by EOP

Weight	Factorial Effect
1	$C, Cn, n$
2	$CC, CCn$
2.5	$CCnn, Cnn, nn$
3	$CCC, CCCn, CCCnn$
3.5	$CCCnnn, CCnnn, Cnnn, nnn$
4	$CCCC, CCCCn, CCCCnn, CCCCnnn$
4.5	$CCCCnnnn, CCCnnnn, CCnnnn, Cnnnn, nnnn$
...	.....

interested in effects of order higher than 5. Additional assumptions can be considered:

(A.1) All effects with order higher than or equal to 4 are negligible.

(A.2) All effects with order higher than or equal to 3 are negligible.

Applying (A.1) and the EOP leads to five groups of effects in the descending order of importance:

$$\begin{aligned} \mathcal{E}_1 = \{C, Cn, n\} &> \mathcal{E}_2 = \{CC, CCn\} > \mathcal{E}_{2.5} = \{Cnn, nn\} \\ &> \mathcal{E}_3 = \{CCC\} > \mathcal{E}_{3.5} = \{nnn\}. \end{aligned} \tag{15}$$

Based on a different argument and weight assignment, Bingham and Sitter (2000) rank-ordered

the factorial effects with order less than 4 as follows:

$$\begin{aligned} \mathcal{E}'_1 = \{C, n\} &> \mathcal{E}'_{1.5} = \{Cn\} > \mathcal{E}'_2 = \{CC, nn\} \\ &> \mathcal{E}'_{2.5} = \{CCn, Cnn\} > \mathcal{E}'_3 = \{CCC, nnn\}. \end{aligned} \quad (16)$$

The major difference concerns the control-by-noise interactions,  $Cn$ ,  $CCn$  and  $Cnn$ , which are ranked higher in our approach and is justified in the previous discussion. The work in the remaining part of the paper is completely different from theirs.

## 4 CRITERIA FOR SELECTING SINGLE ARRAYS

### 4.1 Optimality Criteria for Fractional Factorial Design Revisited

For a given run size and fraction index, fractional factorial designs with less severe effect aliasing are considered to be better. A formal measure of the aliasing severity is thus needed. Suppose the number of factors is  $l$ . The *aliasing type*  $i \sim j$  refers to the aliasing between an effect of order  $i$  and another effect of order  $j$ , where  $1 \leq i \leq j \leq l$ . The type  $l \sim l$  is not possible. The types  $1 \sim 1$ ,  $l-1 \sim l$ ,  $l-1 \sim l-1$  and  $l-2 \sim l$  do not appear in designs with resolution III or higher, because these types will lead to defining words of length one or two. If  $i_1 \sim j_1$  is considered to be more severe than  $i_2 \sim j_2$ , it is written as  $i_1 \sim j_1 > i_2 \sim j_2$ . It is helpful to rank all the aliasing types in the order of severity. Clearly  $1 \sim 2$  is the most severe type, which is followed by  $2 \sim 2$  and  $1 \sim 3$ . Arguably,  $2 \sim 2$  is more severe than  $1 \sim 3$ . Two ordering schemes are considered below.

Scheme 1:

- (i)  $i_1 \sim j_1 > i_2 \sim j_2$ , if  $i_1 + j_1 < i_2 + j_2$ ;
- (ii)  $i_1 \sim j_1 > i_2 \sim j_2$ , if  $i_1 + j_1 = i_2 + j_2$  and  $j_1 - i_1 < j_2 - i_2$ .

For  $l = 6$ , the aliasing types can be rank-ordered as follows:

$$\begin{aligned} 1 \sim 2 &> 2 \sim 2 > 1 \sim 3 > 2 \sim 3 > 1 \sim 4 > 3 \sim 3 > 2 \sim 4 > 1 \sim 5 > 3 \sim 4 \\ &> 2 \sim 5 > 1 \sim 6 > 4 \sim 4 > 3 \sim 5 > 2 \sim 6 > 4 \sim 5 > 3 \sim 6. \end{aligned} \quad (17)$$

Scheme 2:

- (i)  $i_1 \sim j_1 > i_2 \sim j_2$ , if  $j_1 < j_2$ ;
- (ii)  $i_1 \sim j_1 > i_2 \sim j_2$ , if  $j_1 = j_2$  and  $i_1 < i_2$ .

For  $l = 6$ , the aliasing types can be rank-ordered as follows:

$$1 \sim 2 > 2 \sim 2 > 1 \sim 3 > 2 \sim 3 > 3 \sim 3 > 1 \sim 4 > 2 \sim 4 > 3 \sim 4 > 4 \sim 4$$

$$> 1 \sim 5 > 2 \sim 5 > 3 \sim 5 > 4 \sim 5 > 1 \sim 6 > 2 \sim 6 > 3 \sim 6. \quad (18)$$

Let  $N_{i \sim j}$  denote the number of pairs of aliased effects of the type  $i \sim j$ . Noting that a pair of aliased effects of a given type can be derived from various defining words in the defining contrast subgroup,  $N_{i \sim j}$  are related to the wordlength pattern in the following equation,

$$N_{i \sim j} = \sum_{k>0} \binom{[l - (i + j - 2k)]^+}{k} d(i - k, j - k) A_{i+j-2k} + d(i, j) A_{i+j}, \quad (19)$$

where  $d(i, j) = \binom{i+j}{i}$  for  $i \neq j$ ,  $= \frac{1}{2} \binom{i+j}{i}$  for  $i = j \neq 0$ , and  $d(0, 0) = 0$ . (Its derivation is given in Appendix A). Imposing an aliasing severity order by either scheme will result in a numerical summary of the aliasing severity of the corresponding design. To identify designs with least aliasing severity is equivalent to sequentially minimizing  $N_{i \sim j}$ . Equation (19) shows that  $N_{i \sim j}$  are functions of the wordlength pattern  $W = (A_1, A_2, \dots, A_l)$ . Hence, the procedure is to sequentially minimize certain functions of the wordlength patterns. Applying mathematical induction, it can be easily shown that sequentially minimizing  $N_{i \sim j}$  according to ordering scheme 1 or 2 is equivalent to sequentially minimizing  $A_i$ , which leads to the minimum aberration criterion. For example, if the total number of factors is 6,  $N_{i \sim j}$  can be calculated from  $W = (A_1, A_2, A_3, A_4, A_5, A_6)$  as follows:  $N_{1 \sim 2} = 3A_3$ ,  $N_{2 \sim 2} = 3A_4$ ,  $N_{1 \sim 3} = 4A_4$ ,  $N_{2 \sim 3} = 9A_3 + 10A_5$ ,  $N_{1 \sim 4} = 3A_3 + 5A_5$ ,  $N_{3 \sim 3} = 6A_4 + 10A_6$ ,  $N_{2 \sim 4} = 8A_4 + 15A_6$ . Sequentially minimizing  $N_{1 \sim 2}$ ,  $N_{2 \sim 2}$ ,  $N_{1 \sim 3}$ ,  $N_{2 \sim 3}$ ,  $N_{1 \sim 4}$ ,  $N_{3 \sim 3}$  and  $N_{2 \sim 4}$  based on either scheme leads to the minimum aberration criterion which sequentially minimizes  $A_3$ ,  $A_4$ ,  $A_5$  and  $A_6$ .

Minimizing the number of aliased pairs does not necessarily result in maximizing the number of clear effects. These two concepts are very different. Many supporting examples can be found in Appendix 4A of Wu and Hamada (2000).

## 4.2 Criteria for Selecting Optimal Single Arrays

The single array  $S(k_C, k_n, p)$  is uniquely determined by its defining contrast subgroup  $\mathcal{G}$ . In parameter design, defining words of the same length cannot be treated equally, because they may belong to different types. In general, for  $1 \leq k \leq k_C + k_n$ , a word of length  $k$  can be one of the types in  $\{e_{i,j} : i + j = k, 0 \leq i \leq k_C, 0 \leq j \leq k_n\}$ . Let  $A_{i,j}$  be the number of effects of the type  $e_{i,j}$  in  $\mathcal{G}$ , and  $A = (A_{i,j})$  a matrix with entries  $A_{i,j}$  where  $0 \leq i \leq k_C$  and  $0 \leq j \leq k_n$ .  $A$  is called the *wordtype pattern* for  $S(k_C, k_n, p)$ . Based on the wordtype pattern  $A$ , general criteria for selecting single arrays will be developed along the lines of the minimum aberration criterion.

For simplicity, we use  $(i, j)$  instead of  $e_{i,j}$ . If two effects  $(i_1, j_1)$  and  $(i_2, j_2)$  are aliased, it is written as  $(i_1, j_1) \sim (i_2, j_2)$ . Define  $N_{(i_1, j_1) \sim (i_2, j_2)}$  to be the number of pairs of aliased effects of the type  $(i_1, j_1) \sim (i_2, j_2)$ . Straightforward extension of (19) leads to

$$N_{(i_1, j_1) \sim (i_2, j_2)} = \sum_{k_1=0}^{i_1 \wedge i_2} \sum_{k_2=0}^{j_1 \wedge j_2} \binom{k_C + 2k_1 - i_1 - i_2}{k_1} \binom{k_n + 2k_2 - j_1 - j_2}{k_2} d(i_1 - k_1, i_2 - k_1; j_1 - k_2, j_2 - k_2) A_{i_1+i_2-2k_1, j_1+j_2-2k_2}, \quad (20)$$

where  $i \wedge j = \min(i, j)$  for integers  $i$  and  $j$ , and  $d(0, 0, 0, 0) = 0$ ,  $d(x, y; u, v) = \frac{1}{2} \begin{pmatrix} x+y \\ x \end{pmatrix} \begin{pmatrix} u+v \\ u \end{pmatrix}$  for  $x = y$ ,  $u = v$ , and  $x^2 + y^2 + u^2 + v^2 \neq 0$ ; otherwise,  $d(x, y; u, v) = \begin{pmatrix} x+y \\ x \end{pmatrix} \begin{pmatrix} u+v \\ u \end{pmatrix}$ . The *group aliasing type*  $i \approx j$  is defined to be the aliasing between an effect in  $\mathcal{E}_i$  and an effect in  $\mathcal{E}_j$  where  $i$  and  $j$  are from  $\{1, 2, 2.5, 3, \dots, l\}$  and  $i \leq j$ . Two schemes are considered for ordering the group aliasing types.

Scheme 1:

$$i_1 \approx j_1 > i_2 \approx j_2 \text{ if } i_1 + j_1 < i_2 + j_2, \text{ or } j_1 - i_1 < j_2 - i_2 \text{ when } i_1 + j_1 = i_2 + j_2. \quad (21)$$

Scheme 2:

$$i_1 \approx j_1 > i_2 \approx j_2 \text{ if } j_1 < j_2 \text{ or } i_1 < i_2 \text{ when } j_1 = j_2. \quad (22)$$

Let  $N_{i \approx j}$  denote the number of aliased pairs of the type  $i \approx j$ . It can be easily calculated from  $N_{(i_1, j_1) \sim (i_2, j_2)}$  according to the definition,

$$N_{i \approx j} = \sum_{(i_1, j_1) \in \mathcal{E}_i, (i_2, j_2) \in \mathcal{E}_j} N_{(i_1, j_1) \sim (i_2, j_2)}.$$

For example, since  $\mathcal{E}_1 = \{C, Cn, n\}$  and  $\mathcal{E}_2 = \{CC, Cn\}$ ,

$$N_{1 \approx 2} = N_{(1,0) \sim (2,0)} + N_{(1,0) \sim (2,1)} + N_{(1,1) \sim (2,0)} + N_{(0,1) \sim (2,0)} + N_{(0,1) \sim (2,1)}.$$

Based on (20),  $N_{i \approx j}$  can be calculated from the wordtype pattern  $(A_{i,j})_{0 \leq i \leq k_C, 0 \leq j \leq k_n}$ . Applying the ordering scheme in (21) or (22),  $N_{i \approx j}$  can be rank-ordered based on their indices. By sequentially minimizing  $N_{i \approx j}$ , we can obtain single arrays with minimum aliasing severity in terms of the number of aliased pairs of effects. Because  $N_{i \approx j}$  are functions of  $A_{i,j}$ , sequentially minimizing  $N_{i \approx j}$  is equivalent to minimizing a sequence of functions of  $A_{i,j}$ . Therefore, general criteria based on  $(A_{i,j})$  can be proposed to distinguish different single arrays. A complete development would take much effort and is left for future research. Here, a simplified yet

practically important case is considered. Under the assumption (A.2) in Section 3, there are only three groups of effects,

$$\mathcal{E}_1 = \{C, Cn, n\} > \mathcal{E}_2 = \{CC\} > \mathcal{E}_{2.5} = \{nn\}. \quad (23)$$

According to (21), the group aliasing types involving  $\mathcal{E}_1$ ,  $\mathcal{E}_2$  and  $\mathcal{E}_{2.5}$  are rank-ordered as

$$1 \approx 1 > 1 \approx 2 > 1 \approx 2.5 > 2 \approx 2 > 2 \approx 2.5 > 2.5 \approx 2.5; \quad (24)$$

and, according to (22), as

$$1 \approx 1 > 1 \approx 2 > 2 \approx 2 > 1 \approx 2.5 > 2 \approx 2.5 > 2.5 \approx 2.5. \quad (25)$$

Notice that (24) and (25) are slightly different. The relative positions of  $1 \approx 2.5$  and  $2 \approx 2$  are switched in (25). In the following, only (25) will be used. Define  $J = (J_1, J_2, J_3, J_4, J_5, J_6)$  as follows:

$$J_1 = N_{1 \approx 1} = 4A_{2,1} + 4A_{1,2} + 4A_{2,2}, \quad (26)$$

$$J_2 = N_{1 \approx 2} = 3A_{3,0} + 3A_{3,1} + A_{2,1}, \quad (27)$$

$$J_3 = N_{1 \approx 2.5} = A_{1,2} + 3A_{1,3} + 3A_{0,3}, \quad (28)$$

$$J_4 = N_{2 \approx 2} = 6A_{4,0}, \quad (29)$$

$$J_5 = N_{2 \approx 2.5} = A_{2,2}, \quad (30)$$

$$J_6 = N_{2.5 \approx 2.5} = 6A_{0,4}. \quad (31)$$

$J$  is called the *aliasing index vector*. If two single arrays have the same  $J$ , they are said to be  $J$ -equivalent. Based on  $J$ , a minimum  $J$ -aberration criterion can be defined.

**Definition 1 (Minimum  $J$ -aberration)** *For two non-equivalent single arrays  $S_1$  and  $S_2$  which are not  $J$ -equivalent, let  $i_0$  be the smallest  $i$  such that  $J_i(S_1) \neq J_i(S_2)$ . If  $J_{i_0}(S_1) < J_{i_0}(S_2)$ , then  $S_1$  is said to have less  $J$ -aberration than  $S_2$ . If there are no other single arrays with less  $J$ -aberration than  $S_1$ ,  $S_1$  is said to have minimum  $J$ -aberration.*

The simplicity of the aliasing index vector  $J$  is due to the assumption (A.2). First, the defining words with length 5 or higher are not considered. Second, the induced aliasing patterns from the defining words with length less than or equal to 4 do not need to be considered either.

For instance, suppose there is a defining word  $C_1C_2n_1$ , then all possible basic aliasing pairs are  $C_1 = C_2n_1$ ,  $C_2 = C_1n_1$  and  $n_1 = C_1C_2$ . For any other control factor  $C_3$  and noise factor  $n_2$ , there are 6 induced confounded pairs:  $C_1C_3 = C_2C_3n_1$ ,  $C_2C_3 = C_1C_3n_1$ ,  $n_1C_3 = C_1C_2C_3$ ,  $C_1n_2 = C_2n_1n_2$ ,  $C_2n_2 = C_1n_1n_2$ ,  $n_1n_2 = C_1C_2n_2$ . Each of them involves effects with order at least 3 which are assumed to be negligible. Therefore, these induced pairs are not counted.

Because of combinatorial complexity, it is not advisable to employ only one criterion, especially when no model is specified. The clear estimation index  $\alpha$  defined in (14) can be used as an alternative for the evaluation of a single array.

**Definition 2 ( $\alpha$ -admissibility).** *A single array  $S_1$  is said to be  $\alpha$ -inadmissible if there exists another single array  $S_2$  such that  $\alpha^1(i) \leq \alpha^2(i)$  for  $1 \leq i \leq 5$  and at least one of the inequalities is strict. Otherwise  $S_1$  is said to be  $\alpha$ -admissible.*

$J$ -aberration and  $\alpha$ -admissibility will be used to measure the goodness of single arrays.

## 5 CONSTRUCTION METHOD

Single arrays with 8, 16, 32 and 64 runs are of practical importance. Overall good single arrays based on the criteria proposed in Section 4.2 need to be selected and tabulated. All non-isomorphic single arrays need to be constructed and compared so as not to miss any good candidate. Recall that a necessary condition for two single arrays to be isomorphic is that their basic frames are isomorphic fractional factorial designs. For a given basic frame, the columns can be assigned to the control factors and the noise factors in  $\binom{l}{k_C}$  different ways, where  $l = k_C + k_n$ . Therefore the classification of  $S(k_C, k_n, p)$  can be divided into two steps:

- 1). Construct all non-isomorphic  $2^{l-p}$  designs as non-isomorphic basic frames.
- 2). For each basic frame, construct non-isomorphic single arrays from all possible candidates generated by different column assignments.

The non-isomorphic 8-, 16- and 32-run fractional factorial designs are available from Chen, Sun and Wu (1993). Only Step 2 need to be carried out for these cases. For 64-run single arrays, Chen, Sun and Wu (1993) only keep designs with resolution IV or higher. For single arrays, designs with resolution III may be good basic frames, so Step 1 need to be carried out. By definition, single arrays with different wordtype matrices are non-isomorphic, but single arrays with the same wordtype matrix are not necessarily isomorphic. A counterexample can be produced by modifying the work in Chen and Lin (1991). Thus a complete isomorphism



check is required to discriminate arrays with the same wordtype matrix. Let  $D_\eta$  denote the design matrix of a single array, where  $\eta$  is the indicator of the control columns and the noise columns, i.e.,  $\eta_i = 0$  (and resp. 1) if the  $i^{\text{th}}$  column is assigned to a control factor (resp. a noise factor). The generator matrix of  $D_\eta$  has the form  $\begin{pmatrix} I_{l-m} \\ B \end{pmatrix}_\eta$ . The following theorem can be used for isomorphism check.

**Proposition 1** *Suppose  $D_{\eta_1}$  and  $D_{\eta_2}$  are two single arrays with the same basic frame and the generating matrices  $\begin{pmatrix} I_{l-m} \\ B \end{pmatrix}_{\eta_1}$  and  $\begin{pmatrix} I_{l-m} \\ B \end{pmatrix}_{\eta_2}$ . Then  $D_{\eta_1}$  and  $D_{\eta_2}$  are isomorphic if and only if there exists a permutation  $\pi$  such that  $\pi * \eta_2 = \eta_1$ ,  $\pi * \begin{pmatrix} I_{l-m} \\ B \end{pmatrix} = \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$  and  $C_2 C_1^{-1} = B$  if  $\pi$  is treated as a row permutation operator.*

Its proof is given in the Appendix.

## 6 HIGHLIGHTS ON THE TABLES OF SINGLE ARRAYS

Since noise factors are hard to control, the number of noise factors included in parameter design experiments is often small. In the paper, we only consider  $k_n \leq 3$ . Applying the procedure discussed in the previous section, complete tables of non-isomorphic single arrays of 8, 16 and 32 runs are obtained, so are 64-run single arrays with  $k_C + k_n \leq 15$ . For fixed  $k_C$  and  $k_n$ , good single arrays based on  $J$  and  $\alpha$  are included in Appendices C.1-C.4. In each case, only a few single arrays are selected due to space limitation. More extensive tables are available in Zhu (2000). In each table, the first three columns are  $k_C$ ,  $k_n$  and  $p$ , which correspond to the number of control factors, the number of noise factors and the fraction index. The column denoted by  $DC$  gives the  $p$  independent defining words in terms of their positions in the basic design matrix in Appendix B;  $N$  indicates the noise columns in the basic frame generated by the independent defining words. For the 8- and 16-run tables, the aliasing index vector  $J$  is included. For most 32- and 64-run single arrays,  $J$  becomes too large to be included in the tables. By applying the formulae in the definition of  $J$ , it can be calculated from the wordtype matrix. The column  $A$  lists part of the wordtype pattern matrix,  $(A_{3,0}, A_{2,1}, A_{1,2}, A_{0,3}, A_{4,0}, A_{3,1}, A_{2,2}, A_{1,3})$ . The last column of each table reports the clear estimation index,  $\alpha = (N_C, N_n, N_{CC}, N_{Cn}, N_{nn})$ . For given  $k_C$ ,  $k_n$  and  $p$ , the corresponding single arrays are listed in the order of the  $J$ -aberration criterion. The first or the first few arrays are minimum  $J$ -aberration single arrays, because different single arrays may share the same  $J$ . According to Lemma 1, for run size  $2^k$ , cross arrays do not exist for all possible  $k_C$  and  $k_n$ . For  $k_n = 1$ , they exist for  $k_C \leq 2^{k-1} - 1$ ; for  $k_n = 2$

or 3, they exist for  $k_c \leq 2^{k-2} - 1$ . These conditions explain why cross arrays are not listed in some part of the tables. Cross arrays are marked by \* in the tables.

We use the following example to illustrate the usage of the tables. Suppose a 32-run single array is needed to study seven control factors and two noise factors, i.e.  $k_C = 7$ ,  $k_n = 2$  and  $p = 4$ . There are four corresponding single arrays listed in the table in Appendix C.3. Suppose the first one is chosen. Since there are nine factors and 32 runs, the basic frame is a  $2^{9-4}$  design. The nine columns are denoted by the letters: 1, 2, 3, 4, 5, 6, 7, 8, 9. The first five columns are independent, and the remaining four columns are generated by the four defining words given in *DC*, which correspond to the columns 7, 11, 13 and 30 in the basic design matrix in Appendix B. Since the columns are  $(1, 1, 1, 0, 0)^t$ ,  $(1, 1, 0, 1, 0)^t$ ,  $(1, 0, 1, 1, 0)^t$  and  $(0, 1, 1, 1, 1)^t$ , the defining words for these four columns are 6=123, 7=124, 8=134, and 9=2345. In the *N* column, (5,9) indicates that columns 5 and 9 of the basic frame are assigned to the two noise factors;  $\alpha = (7, 2, 0, 14, 1)$  reports that all the seven control main effects, the two noise main effects and the 14 *Cn* effects are clear, but none of the control-by-control interactions are clear.

The wordtype matrices and clear estimation indices listed in the tables reflect the complexity in classifying single arrays. For example, for  $k_C = 6$ ,  $k_n = 3$  and  $p = 4$ , the following non-isomorphic single arrays are given in Appendix D.3:

$$S_1 : \quad 6 = 123, 7 = 124, 8 = 134, 9 = 2345, \text{ noise columns: } 1, 5, 9,$$

$$S_2 : \quad 6 = 12, 7 = 13, 8 = 23, 9 = 12345, \text{ noise columns: } 4, 5, 9,$$

$$S_3 : \quad 6 = 12, 7 = 13, 8 = 23, 9 = 45, \text{ noise columns: } 4, 5, 9.$$

$S_1$  is listed as the first single array according to the aliasing index vector  $J$ , which is (0, 12, 0, 18, 0, 0). All its control and noise main effects are clear. Twelve of the 18 *Cn* effects are clear, which are {25, 29, 35, 39, 45, 49, 56, 57, 58, 69, 79, 89} and the other *Cn* effects are eligible. The eligible sets that include at least one *Cn* effect are

$$12 = 36 = 47, 13 = 26 = 48, 14 = 27 = 38,$$

$$16 = 23 = 78, 17 = 24 = 68, 18 = 34 = 67.$$

In addition, three noise-by-noise interactions {15, 19, 59} are clear. The aliasing index  $J$  of  $S_2$  is also (0, 12, 0, 18, 0, 0). But  $S_2$  is quite different from  $S_1$  in terms of  $\alpha$ . All its noise main effects, noise-by-noise and control-by-noise interactions are clear. The six control main effects

are only eligible. The eligible sets are

$$1 = 26 = 37, 16 = 2 = 38, 17 = 28 = 3,$$

$$12 = 6 = 78, 13 = 68 = 7, 23 = 67 = 8.$$

It is easy to show that  $S_3$  is a cross array, i.e.,  $S_3 = 2^{6-3} \otimes 2^{3-1}$ . The crossing structure guarantees that all the  $Cn$  effects are clear. But in  $S_3$ , the control and noise main effects are only eligible. Its vector  $J$  is  $(0, 12, 3, 18, 0, 0)$ . Compared to  $S_1$  and  $S_2$ ,  $S_3$ , though a cross array, can be viewed as inferior.

Several important issues will be briefly discussed here. As indicated earlier, minimum aberration designs do not necessarily provide the best basic frames for single arrays. This is evident for single arrays with large fraction index  $p$  or a large number of noise factors ( i.e., close values of  $k_n$  and  $k_C$ ). For small  $p$  and  $k_n$ , minimum aberration designs lead to minimum  $J$ -aberration single arrays. For example, minimum  $J$ -aberration 64-run single arrays  $S(7, 1, 2)$ ,  $S(6, 2, 2)$ ,  $S(5, 3, 2)$ ,  $S(8, 1, 3)$ ,  $S(7, 2, 3)$ ,  $S(6, 3, 3)$ ,  $S(9, 1, 4)$  and  $S(8, 2, 4)$  use the corresponding minimum aberration designs as the basic frame. But the  $J$ -minimum aberration single arrays  $S(7, 3, 4)$ ,  $S(9, 2, 5)$ ,  $S(8, 3, 5)$ ,  $S(11, 1, 6)$ ,  $S(10, 2, 6)$ ,  $S(9, 3, 6)$ ,  $S(12, 1, 7)$  and  $S(12, 2, 7)$  are not based on the corresponding minimum aberration designs.

The inconsistency between minimum aberration and the maximum number of clear effects carries over to the minimum  $J$ -aberration single arrays. There are many cases in which the minimum  $J$ -aberration single arrays are also optimal in terms of the clear estimation index  $\alpha$ . Minimum  $J$ -aberration single arrays are  $\alpha$ -admissible in most cases. But there are exceptions. For example, the first and second arrays for  $k_C = 7$ ,  $k_n = 3$  and  $p = 5$  have  $\alpha^1 = (4, 0, 0, 6, 0)$  and  $\alpha^2 = (7, 0, 0, 14, 0)$ . Their aliasing index vectors are  $J^1 = (0, 21, 3, 6, 0, 0)$  and  $J^2 = (0, 24, 3, 42, 0, 0)$ . Though the first array has minimum  $J$ -aberration, obviously it is  $\alpha$ -inadmissible.

Cross arrays are often not good according to the minimum  $J$ -aberration criterion and can even be  $\alpha$ -inadmissible. Because cross arrays guarantee that all the  $Cn$  effects are clear, they are usually ranked among the top 10 to 20 based on  $J$ , but many better single arrays are available. Two examples are given for illustration. For  $k_C = 6$ ,  $k_n = 2$  and  $p = 3$ , the minimum  $J$ -aberration single array, denoted by  $S_1$ , has  $\alpha = (6, 2, 0, 12, 1)$ . The cross array  $S_3$  has  $\alpha = (0, 2, 0, 12, 1)$ . In both arrays, all the  $Cn$  effects are clear. All the control and noise main effects are clear in  $S_1$ , while they are only eligible in  $S_3$ . Another example is for

$k_C = 6$ ,  $k_n = 3$  and  $p = 3$ . Denote the first and the fourth arrays by  $S_1$  and  $S_4$ , where  $S_1$  has  $\alpha = (6, 3, 9, 18, 3)$ , and  $S_4$  has  $\alpha = (6, 0, 0, 18, 0)$ . The former has minimum  $J$ -aberration while the latter is a cross array. From the two  $\alpha$  vectors, it is clear that  $S_1$  is much better than  $S_4$ . There are cases in which cross arrays are winners in terms of the number of clear  $Cn$  effects. When the fraction index  $p$  is large, the capacity of a fractional factorial design is limited and balancing estimation among different effects becomes difficult. The crossing structure puts one type of effects, namely  $Cn$  effects, as the top priority for estimation. For example, for  $k_C = 11$ ,  $k_n = 1$ , and  $p = 7$ , the listed arrays are  $S_1$ ,  $S_2$  and  $S_3$  with  $\alpha = (0, 1, 1, 0, 0)$ ,  $\alpha = (11, 1, 0, 0, 0)$ , and  $\alpha = (0, 1, 0, 11, 0)$  respectively.  $S_1$  is a minimum  $J$ -aberration array,  $S_2$  is based on the  $2^{12-7}$  minimum aberration design, and  $S_3$  is a cross array. Only the cross array can guarantee that all the  $Cn$  effects are clear.

## 7 SUMMARY

Based on the argument that control-by-noise interactions play a pivotal role in parameter design experiments, a new effect ordering principle is proposed for ranking the relative importance of factorial effects. This principle together with the concepts of aliasing type and wordtype pattern leads to the minimum  $J$ -aberration criterion, which is an extension of the minimum aberration criterion for regular fractional factorial designs. Good single arrays can be chosen based on the  $J$ -aberration criterion and the clear estimation index vector  $\alpha$ . The collection of useful single arrays given in the Appendix can aid experimenters in choosing appropriate experimental plans. For space limitation, only two-level regular fractions are considered. Extensions to more than two levels and to nonregular fractions will be of interest.

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## APPENDIX A: PROOFS

### Proof of (19)

Let  $N_{i \sim j}$  denote the number of pairs of aliased effects of type  $i \sim j$ . A pair of aliased effects of type  $i \sim j$  can be derived from different defining words in the defining contrast subgroup. Let  $(E_1, E_2)$  denote a pair of aliased effects of type  $i \sim j$ , where  $E_1$  has order  $i$ ,  $E_2$  has order  $j$  and  $i \leq j$ . Define  $\Theta_k$  to be the collection of  $(E_1, E_2)$  such that  $E_1$  and  $E_2$  have exactly  $k$  factors in common, where  $0 \leq k \leq i$ . For  $k = 0$ , suppose  $(E_1, E_2)$  is an arbitrary pair in  $\Theta_0$ . It is induced from a defining word of length  $i + j$ . Every defining word of length  $i + j$  can induce  $d(i, j)$  different pairs of aliased effects of type  $i \sim j$  which belong to  $\Theta_0$ , where

$$d(i, j) = \begin{cases} \binom{i+j}{i} & \text{if } i \neq j; \\ \frac{1}{2} \binom{i+j}{i} & \text{if } i = j \neq 0. \end{cases}$$

In addition, define  $d(0, 0) = 0$ . If  $(E_1, E_2)$  and  $(E'_1, E'_2)$  are induced from two different defining words of length  $i + j$ , they must be different. Therefore,  $|\Theta_0| = d(i, j)A_{i+j}$ . For  $k > 0$ ,  $\Theta_k$  contains the pairs of aliased effects which share exactly  $k$  factors. Suppose  $(E_1, E_2) \in \Theta_k$ , which is induced from a defining word of length  $i + j - 2k$ . Every defining word of length  $i + j - 2k$  can generate  $\binom{[l - (i + j - 2k)]^+}{k} d(i - k, j - k)$  pairs of  $(E_1, E_2) \in \Theta_k$ . Different defining words of the same length  $i + j - 2k$  must generate different pairs of aliased effects belonging to  $\Theta_k$ . Therefore,

$$|\Theta_k| = \binom{[l - (i + j - 2k)]^+}{k} d(i - k, j - k)A_{i+j-2k}.$$

Since  $\Theta_0, \dots, \Theta_i$  are mutually exclusive, it leads to (19)

### Proof of Proposition 1

Suppose there exists a row permutation  $\pi$ , such that  $\pi * \eta_2 = \eta_1$ ,  $\pi * \begin{pmatrix} I_{l-m} \\ B \end{pmatrix} = \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$  and  $C_2 C_1^{-1} = B$ . Since  $D'_{\eta_2} = \left\{ \begin{pmatrix} I_{l-m} \\ B \end{pmatrix}_{\eta_2} u : u \in \mathbf{F}_2^{l-m} \right\}$ ,

$$\begin{aligned} \pi * D'_{\eta_2} &= \left\{ \pi * \begin{pmatrix} I_{l-m} \\ B \end{pmatrix}_{\eta_2} u : u \in \mathbf{F}_2^{l-m} \right\} = \left\{ \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}_{\eta_1} u : u \in \mathbf{F}_2^{l-m} \right\} \\ &= \left\{ \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}_{\eta_1} C_1^{-1} C_1 u, u \in \mathbf{F}_2^{l-m} \right\} = \left\{ \begin{pmatrix} I_{l-m} \\ B \end{pmatrix}_{\eta_1} v : v \in \mathbf{F}_2^{l-m} \right\} = D'_{\eta_1} \end{aligned}$$

Hence  $D_{\eta_1}$  and  $D_{\eta_2}$  are isomorphic. Suppose  $D_{\eta_1}$  and  $D_{\eta_2}$  are isomorphic. Then there exists a row permutation  $\pi$  such that  $\pi * \eta_2 = \eta_1$ ,  $\pi * \begin{pmatrix} I_{l-m} \\ B \end{pmatrix} = \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$  and the columns of  $\begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$  belong to  $D'_{\eta_1}$ . Hence there exists a matrix  $M$ ,

$$\begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \begin{pmatrix} I_{l-m} \\ B_1 \end{pmatrix} M$$

so we have  $C_1 = M$  and  $c_2 = B_1 M$ . Because  $M$  must be nonsingular, the theorem is proved.

## APPENDIX B

(Design matrices for 16, 32 and 64-run designs. For 16-run designs, it consists of the first 4 rows and 15 columns; for 32-run designs, it consists of the first 5 rows and 31 columns; and for 64-run designs, it is the whole matrix. Independent columns are numbered 1, 2, 4, 8, 16 and 32 and in bold face.)

<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	5	6	7	<b>8</b>	9	10	11	12	13	14	15	<b>16</b>	17	18	19	20	21
1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1
0	1	1	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1	0	0
0	0	0	1	1	1	1	0	0	0	0	1	1	1	1	0	0	0	0	1	1
0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
<b>22</b>	<b>23</b>	<b>24</b>	<b>25</b>	<b>26</b>	<b>27</b>	<b>28</b>	<b>29</b>	<b>30</b>	<b>31</b>	<b>32</b>	<b>33</b>	<b>34</b>	<b>35</b>	<b>36</b>	<b>37</b>	<b>38</b>	<b>39</b>	<b>40</b>	<b>41</b>	<b>42</b>
0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0
1	1	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1
1	1	0	0	0	0	1	1	1	1	0	0	0	0	0	1	1	1	0	0	0
0	0	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	1	1	1
1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1
<b>43</b>	<b>44</b>	<b>45</b>	<b>46</b>	<b>47</b>	<b>48</b>	<b>49</b>	<b>50</b>	<b>51</b>	<b>52</b>	<b>53</b>	<b>54</b>	<b>55</b>	<b>56</b>	<b>57</b>	<b>58</b>	<b>59</b>	<b>60</b>	<b>61</b>	<b>62</b>	<b>63</b>
1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1
1	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1
0	1	1	1	1	0	0	0	0	1	1	1	1	0	0	0	0	1	1	1	1
1	1	1	1	1	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1
0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1

## APPENDIX C

( $k_C$ =number of control factors,  $k_n$ =number of noise factors,  $p$ =fraction index,  $DC$ =defining columns,  $J$ =aliasing index vector,  $A$ =part of wordtype matrix,  $\alpha$ =clear estimation index; a cross array is indicated by \*.)

### 1. 8-Run Single Arrays

$k_c$	$k_n$	$p$	$DC$	$N$	$J$	$A$	$\alpha$
*3	1	1	3	3	030000	10000000	01030
3	1	1	7	4	030000	00000100	31000
3	1	1	3	4	410000	01000000	10210
2	2	1	7	34	400010	00000010	22000
2	2	1	3	12	401000	00100000	00120
2	2	1	3	34	410000	01000000	00021
4	1	2	35	1	410600	01001000	00000
4	1	2	35	5	440000	11000100	00000
3	2	2	35	12	841000	01100100	00000
3	2	2	35	45	1220010	02000010	00000
5	1	3	356	1	8140600	22001200	00000
4	2	3	356	12	16111010	12100210	00000
4	2	3	356	34	2440620	04001020	00000
3	3	3	356	134	2055010	02200111	00000
3	3	3	356	124	2433030	03010030	00000
3	3	3	356	123	2433030	10300030	00000
6	1	4	3567	1	122501800	43003400	00000
5	2	4	3567	12	28221620	21101420	00000
4	3	4	3567	123	36156030	13300331	00000
4	3	4	3567	124	4863660	06011060	00000

## 2. 16-Run Single Arrays

$k_c$	$k_n$	$p$	$DC$	$N$	$J$	$A$	$\alpha$
4	1	1	15	1	000000	00000000	41640
3	2	1	15	12	000000	00000000	32361
*3	2	1	3	34	030000	10000000	02061
2	3	1	15	123	000000	00000000	23163
*2	3	1	3	125	003000	00010000	20160
5	1	2	313	3	060000	10000100	21420
*5	1	2	35	4	060600	20001000	01050
5	1	2	711	1	060600	00001200	51000
5	1	2	313	2	410600	01001000	30330
4	2	2	313	25	401600	00101000	30060
4	2	2	711	13	460010	00000210	42000
3	3	2	313	125	033000	00010100	30060
*3	3	2	312	125	033000	10010000	00090
3	3	2	711	123	433010	00000111	33000
6	1	3	3514	4	0120600	20001200	11110
6	1	3	71113	1	01201800	00003400	61000
*6	1	3	356	4	01201800	40003000	01060
5	2	3	3514	47	860620	20001020	02020
5	2	3	71113	12	8120620	00001420	52000
5	2	3	356	14	8140600	22001200	01051
4	3	3	3514	125	873010	01010210	20020
4	3	3	3510	136	873010	11010110	00040
4	3	3	71113	123	1293030	00000331	43000



7	1	4	3 5 9 14	8	0 21 0 18 0 0	3 0 0 0 3 4 0 0	0 1 0 1 0
7	1	4	7 11 13 14	1	0 21 0 42 0 0	0 0 0 0 7 7 0 0	7 1 0 0 0
*7	1	4	3 5 6 7	4	0 21 0 42 0 0	7 0 0 0 7 0 0 0	0 1 0 7 0
6	2	4	3 5 6 15	4 8	12 12 0 18 3 0	4 0 0 0 3 0 3 0	0 2 0 0 0
6	2	4	7 11 13 14	1 2	12 24 0 18 3 0	0 0 0 0 3 8 3 0	6 2 0 0 0
6	2	4	3 5 6 7	1 4	12 27 0 18 0 0	4 3 0 0 3 4 0 0	0 1 0 6 1
5	3	4	3 5 10 12	1 2 5	16 14 3 0 2 0	1 2 0 1 0 3 2 0	0 0 0 0 0
5	3	4	3 5 6 9	1 4 8	16 14 3 6 2 0	2 2 0 1 1 2 2 0	0 0 0 2 0
8	1	5	3 5 6 9 14	8	4 31 0 30 0 0	5 1 0 0 5 5 0 0	0 0 0 0 0
7	2	5	3 5 6 7 9	4 9	16 21 1 42 3 0	7 0 1 0 7 0 3 0	0 0 0 0 0
6	3	5	3 5 10 12 15	1 2 5	24 27 3 0 3 0	2 3 0 1 0 6 3 0	0 0 0 0 0
9	1	6	3 5 6 9 10 13	7	8 44 0 54 0 0	7 2 0 0 9 7 0 0	0 0 0 0 0
8	2	6	3 5 6 7 9 10	4 9	24 41 1 42 3 0	7 2 1 0 7 6 3 0	0 0 0 0 0
7	3	6	3 5 6 9 14 15	1 2 6	36 43 5 18 3 0	2 4 2 0 3 11 3 1	0 0 0 0 0
10	1	7	3 5 6 9 10 13 14	1	12 60 0 96 0 0	9 3 0 0 16 10 0 0	0 0 0 0 0
9	2	7	3 5 6 7 9 10 12	4 9	32 64 1 60 3 0	8 4 1 0 10 12 3 0	0 0 0 0 0
8	3	7	3 5 6 9 10 13 14	1 3 7	52 63 5 30 5 0	4 6 2 0 5 15 5 1	0 0 0 0 0
11	1	8	3 5 6 9 10 13 14 15	1	16 79 0 156 0 0	12 4 0 0 26 13 0 0	0 0 0 0 0
10	2	8	3 5 6 9 10 13 14 15	1 2	40 93 1 96 3 0	9 6 1 0 16 20 3 0	0 0 0 0 0
9	3	8	3 5 6 7 9 10 11 12	1 3 7	68 91 6 54 7 0	7 7 3 0 9 21 7 1	0 0 0 0 0
12	1	9	3 5 6 7 9 10 11 12 13	2	20 107 0 228 0 0	17 5 0 0 38 17 0 0	0 0 0 0 0
11	2	9	3 5 6 7 9 10 11 12 13	2 3	52 125 1 150 4 0	13 8 1 0 25 26 4 0	0 0 0 0 0
10	3	9	3 5 6 7 9 10 11 12 13	2 3 8	84 129 6 90 9 0	10 9 3 0 15 30 9 1	0 0 0 0 0
13	1	10	3 5 6 7 9 10 11 12 13 14	1	24 138 0 330 0 0	22 6 0 0 55 22 0 0	0 0 0 0 0
12	2	10	3 5 6 7 9 10 11 12 13 14	1 2	64 163 1 228 5 0	17 10 1 0 38 34 5 0	0 0 0 0 0
11	3	10	3 5 6 7 9 10 11 12 13 14	1 2 3	108 168 6 150 12 0	13 12 3 0 25 39 12 1	0 0 0 0 0
14	1	11	3 5 6 7 9 10 11 12 13 14 15	1	28 175 0 462 0 0	28 7 0 0 77 28 0 0	0 0 0 0 0
13	2	11	3 5 6 7 9 10 11 12 13 14 15	1 2	76 210 1 330 6 0	22 12 1 0 55 44 6 0	0 0 0 0 0
12	3	11	3 5 6 7 9 10 11 12 13 14 15	1 2 3	132 219 6 228 15 0	17 15 3 0 38 51 15 1	0 0 0 0 0

### 3. 32-Run Single Arrays

$k_C$	$k_n$	$p$	$DC$	$N$	$A$	$\alpha$
5	1	1	31	1	0 0 0 0 0 0 0 0	5 1 10 5 0
*5	1	1	15	5	0 0 0 0 0 0 0 0	5 1 10 5 0
4	2	1	31	1 2	0 0 0 0 0 0 0 0	4 2 6 8 1
*4	2	1	7	4 5	0 0 0 0 1 0 0 0	4 2 0 8 1
3	3	1	31	1 2 3	0 0 0 0 0 0 0 0	3 3 3 9 3
*3	3	1	3	1 2 6	0 0 0 1 0 0 0 0	3 0 3 9 0
6	1	2	7 27	4	0 0 0 0 1 0 0 0	6 1 9 6 0
*6	1	2	7 11	5	0 0 0 0 3 0 0 0	6 1 0 6 0
6	1	2	7 27	1	0 0 0 0 0 1 0 0	6 1 12 3 0
6	1	2	3 29	3	1 0 0 0 0 0 0 0	3 1 12 6 0
6	1	2	3 29	1	0 1 0 0 0 0 0 0	4 0 14 4 0
5	2	2	7 27	4 5	0 0 0 0 1 0 0 0	5 2 4 10 1
5	2	2	3 29	3 4	1 0 0 0 0 0 0 0	2 2 7 10 1
*5	2	2	3 5	4 5	2 0 0 0 1 0 0 0	0 2 0 10 1
5	2	2	3 29	2 6	0 0 1 0 0 0 0 0	4 0 10 8 0

4	3	2	7 27	4 5 7	0 0 0 0 1 0 0 0	4 3 0 1 2 3
4	3	2	3 29	1 2 6	0 0 0 1 0 0 0 0	4 0 6 1 2 0
*4	3	2	3 28	1 2 6	0 0 0 1 1 0 0 0	4 0 0 1 2 0
7	1	3	7 11 29	5	0 0 0 0 3 0 0 0	7 1 6 7 0
*7	1	3	7 11 13	5	0 0 0 0 7 0 0 0	7 1 0 7 0
7	1	3	7 11 29	1	0 0 0 0 1 2 0 0	7 1 1 1 2 0
7	1	3	3 5 30	4	2 0 0 0 1 0 0 0	2 1 1 1 7 0
6	2	3	7 11 29	5 8	0 0 0 0 3 0 0 0	6 2 0 1 2 1
6	2	3	7 11 29	1 5	0 0 0 0 1 2 0 0	6 2 5 7 1
*6	2	3	3 5 6	4 5	4 0 0 0 3 0 0 0	0 2 0 1 2 1
6	2	3	3 12 21	2 6	1 0 1 0 1 0 0 0	2 0 6 1 0 0
5	3	3	7 11 29	1 5 8	0 0 0 0 1 2 0 0	5 3 0 1 0 3
5	3	3	3 5 30	4 5 8	2 0 0 0 1 0 0 0	0 3 0 1 5 3
5	3	3	3 13 22	1 2 6	0 0 0 1 0 2 0 0	5 0 4 9 0
*5	3	3	3 5 24	4 5 8	2 0 0 1 1 0 0 0	0 0 0 1 5 0
5	3	3	7 11 29	1 2 3	0 0 0 0 0 1 1 1	5 3 7 6 0
8	1	4	7 11 19 29	9	0 0 0 0 6 0 0 0	8 1 0 8 0
8	1	4	7 11 13 30	5	0 0 0 0 7 0 0 0	8 1 7 8 0
*8	1	4	7 11 13 14	5	0 0 0 0 1 4 0 0 0	8 1 0 8 0
8	1	4	7 11 13 30	1	0 0 0 0 3 4 0 0	8 1 1 3 2 0
8	1	4	3 5 6 31	4	4 0 0 0 3 0 0 0	2 1 1 3 8 0
7	2	4	7 11 13 30	5 9	0 0 0 0 7 0 0 0	7 2 0 1 4 1
7	2	4	7 11 13 30	1 5	0 0 0 0 3 4 0 0	7 2 6 8 1
7	2	4	3 5 6 31	4 5	4 0 0 0 3 0 0 0	1 2 6 1 4 1
*7	2	4	3 5 6 7	4 5	7 0 0 0 7 0 0 0	0 2 0 1 4 1
6	3	4	7 11 13 30	1 5 9	0 0 0 0 3 4 0 0	6 3 0 1 2 3
6	3	4	3 5 6 31	4 5 9	4 0 0 0 3 0 0 0	0 3 0 1 8 3
*6	3	4	3 5 6 24	4 5 9	4 0 0 1 3 0 0 0	0 0 0 1 8 0
9	1	5	7 11 19 29 30	1	0 0 0 0 6 4 0 0	9 1 0 0 0
9	1	5	3 5 14 22 25	10	2 0 0 0 6 2 0 0	4 1 0 4 0
9	1	5	3 5 9 17 30	10	4 0 0 0 6 0 0 0	0 1 0 9 0
9	1	5	3 5 9 14 31	5	3 0 0 0 7 1 0 0	2 1 6 6 0
*9	1	5	3 5 9 14 15	5	4 0 0 0 1 4 0 0 0	0 1 0 9 0
8	2	5	3 13 21 25 28	2 6	0 0 1 0 1 4 0 0 0	7 0 0 1 4 0
8	2	5	7 11 19 29 30	1 3	0 0 0 0 3 6 1 0	8 2 0 0 0
7	3	5	3 12 21 26 31	1 2 6	1 0 0 1 1 6 0 0	4 0 0 6 0
7	3	5	3 13 21 25 28	1 2 6	0 0 0 1 7 7 0 0	7 0 0 1 4 0
*7	3	5	3 5 6 7 24	4 5 10	7 0 0 1 7 0 0 0	0 0 0 2 1 0
10	1	6	3 5 14 22 24 31	11	4 0 0 0 6 4 0 0	0 1 1 0 0
10	1	6	7 11 13 14 19 21	5	0 0 0 0 1 8 8 0 0	1 0 1 0 0 0
*10	1	6	3 5 6 9 14 15	5	8 0 0 0 1 8 0 0 0	0 1 0 1 0 0
9	2	6	3 5 9 14 15 18	5 11	4 0 1 0 1 4 0 1 0	0 0 0 1 2 0
9	2	6	3 5 14 22 26 28	1 6	0 1 1 0 1 4 4 0 0	6 0 0 6 0
8	3	6	3 5 14 22 24 31	1 2 6	2 1 0 1 1 8 1 0	1 0 0 1 0
8	3	6	3 5 14 22 26 29	1 2 6	0 1 0 1 5 1 0 1 0	6 0 0 6 0
8	3	6	3 5 6 9 14 31	5 9 11	5 1 0 0 5 5 1 1	0 2 0 1 0 0
8	3	6	3 5 6 9 14 25	5 9 11	5 1 0 1 5 5 1 0	0 0 0 1 2 0

11	1	7	3 5 10 12 19 21 30	12	6 0 0 0 10 6 0 0	0 1 1 0 0
11	1	7	7 11 13 14 19 21 25	5	0 0 0 0 26 12 0 0	11 1 0 0 0
*11	1	7	3 5 6 9 10 13 14	5	12 0 0 0 26 0 0 0	0 1 0 11 0
10	2	7	3 5 6 9 14 15 18	5 12	8 0 1 0 18 0 2 0	0 0 0 10 0
10	2	7	3 5 9 14 22 26 28	1 6	0 2 1 0 18 8 0 0	5 0 0 5 0
9	3	7	3 5 10 12 19 21 30	2 4 8	3 2 0 1 3 11 2 0	1 0 0 1 0
9	3	7	3 5 6 9 22 26 29	1 4 9	3 2 0 1 5 11 2 0	2 0 0 4 0
12	1	8	3 5 10 12 19 21 25 30	13	8 0 0 0 15 8 0 0	0 1 0 0 0
12	1	8	7 11 13 14 19 21 22 25	13	0 0 0 0 39 16 0 0	12 1 0 0 0
*12	1	8	3 5 6 9 10 13 14 15	5	16 0 0 0 39 0 0 0	0 1 0 12 0
11	2	8	3 5 6 9 10 13 14 31	5 13	12 0 0 0 26 0 4 0	0 2 0 6 0
11	2	8	3 5 6 9 10 13 14 17	5 13	12 0 1 0 26 0 3 0	0 0 0 8 0
11	2	8	3 5 9 14 17 22 26 28	1 6	0 3 1 0 26 12 0 0	4 0 0 4 0
10	3	8	3 5 10 12 19 21 25 30	1 2 6	4 3 0 1 5 15 3 0	1 0 0 0 0
13	1	9	3 5 9 14 18 20 23 24 27	9	10 0 0 0 23 12 0 0	0 1 0 0 0
13	1	9	7 11 13 14 19 21 22 25 26	14	0 0 0 0 55 22 0 0 0	13,1,0,0,0
*13	1	9	3 5 6 7 9 10 11 12 13	5	22 0 0 0 55 0 0 0	0 1 0 13 0
12	2	9	3 5 6 9 10 13 14 15 17	5 14	16 0 1 0 39 0 4 0	0 0 0 6 0
11	3	9	3 5 9 14 18 20 26 29 31	1 2 6	5 4 0 1 10 20 4 0	0 0 0 0 0
14	1	10	3 5 9 14 18 20 23 24 27 29	9	12 0 0 0 33 16 0 0	0 1 0 0 0
14	1	10	7 11 13 14 19 21 22 25 26	1	0 0 0 0 77 28 0 0	14 1 0 0 0
			28			
*14	1	10	3 5 6 7 9 10 11 12 13 14	5	28 0 0 0 77 0 0 0	0 1 0 14 0
13	2	10	3 5 6 7 9 10 11 12 13 30	5 15	22 0 0 0 55 0 6 0	0 2 0 2 0
12	3	10	3 5 6 9 14 18 23 25 29 30	1 4 9	8 5 0 1 14 26 5 0	0 0 0 0 0
15	1	11	3 5 9 14 18 20 23 24 27 29	9	15 0 0 0 45 20 0 0	0 1 0 0 0
			31			
15	1	11	7 11 13 14 19 21 22 25 26	1	0 0 0 0 105 35 0 0	15 1 0 0 0
			28 31			
*15	1	11	3 5 6 7 9 10 11 12 13 14	5	35 0 0 0 105 0 0 0	0 1 0 15 0
			15			
14	2	11	3 5 6 7 9 10 11 12 13 14	5 16	28 0 0 0 77 0 7 0	0 2 0 0 0
			31			
13	3	11	3 5 6 9 10 12 17 18 21 30	1 15 16	11 6 0 1 22 33 6 0	0 0 0 0 0
			31			

#### 4. 64-Run Single Arrays

$k_C$	$k_n$	$p$	$DC$	$N$	$A$	$\alpha$
6	1	1	63	1	00000000	6 1 15 6 0
*6	1	1	31	6	00000000	6 1 15 6 0
5	2	1	63	1 2	00000000	5 2 10 10 1
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